Self-Stabilizing Leader Election in Polynomial Steps[1]

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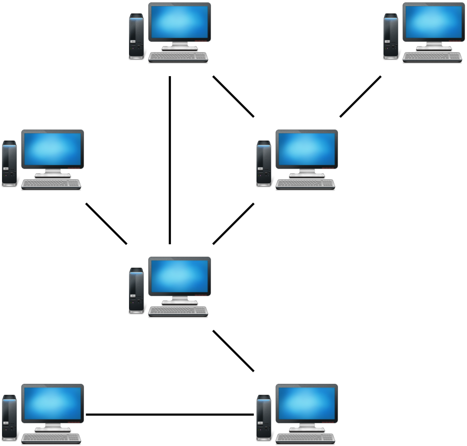
Anaïs Durand Franck Petit

February 16, 2015. LaBRI

[1] This work has been partially supported by the LabEx PERSYVAL-Lab (ANR-11-LABX-0025-01) and the AGIR project DIAMS.

Context

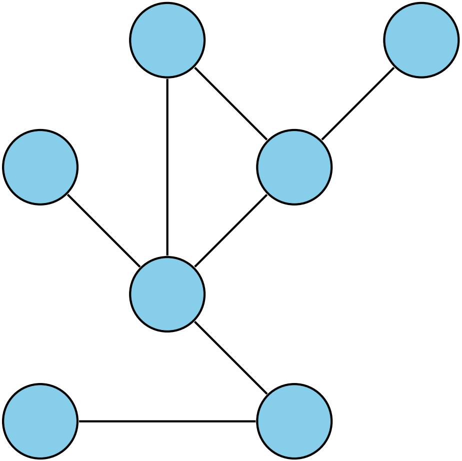
Distributed Systems



Process

- Autonomous
- Interconnected

Distributed Systems



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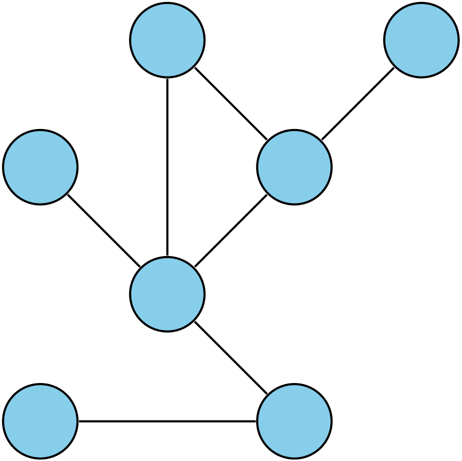

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Hypotheses

- Connected
- Bidirectional
- Identified

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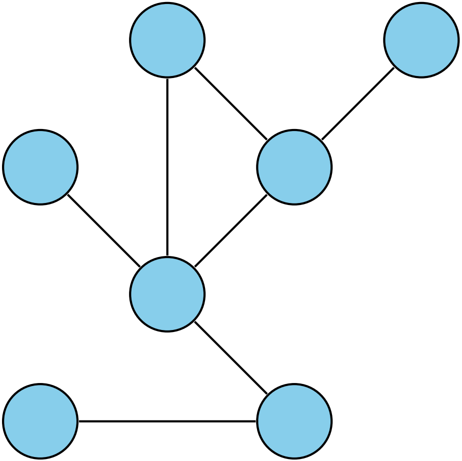

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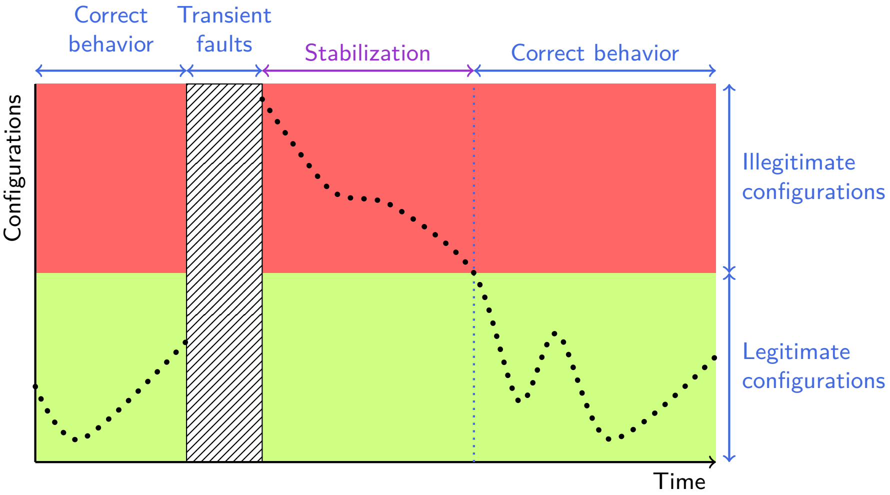
Expected Property

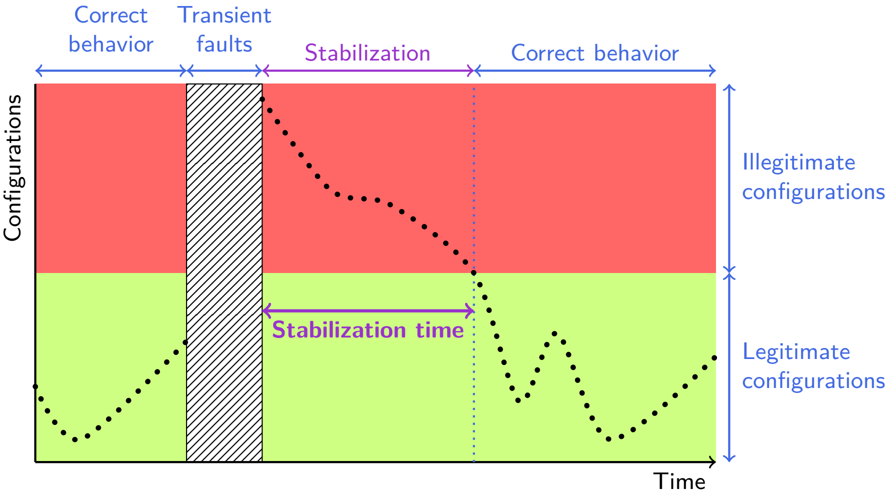
Fault-tolerance

Self-Stabilization[2]



[2] Edsger W. Dijkstra. Self-stabilizing systems in spite of distributed control. 1974

Self-Stabilization[2]



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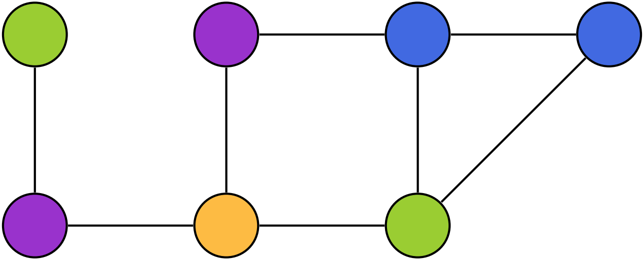
Locally Shared Memory Model

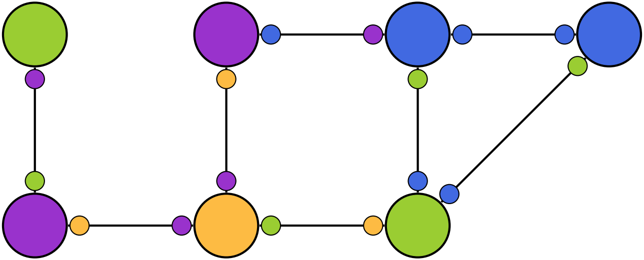
Configuration



Locally Shared Memory Model

Atomic Step

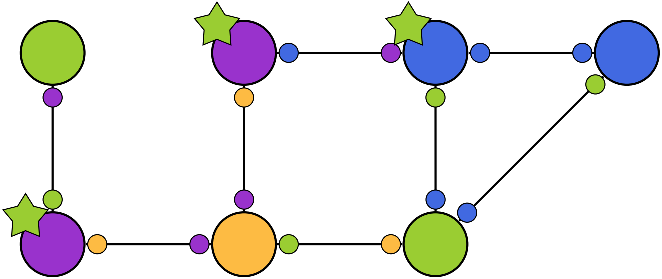
- Reading of the variables of the neighbors



Locally Shared Memory Model

Atomic Step

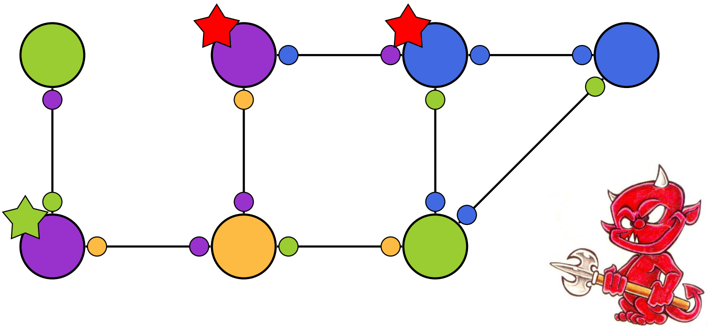
- Reading of the variables of the neighbors
- Enabled nodes



Locally Shared Memory Model

Atomic Step

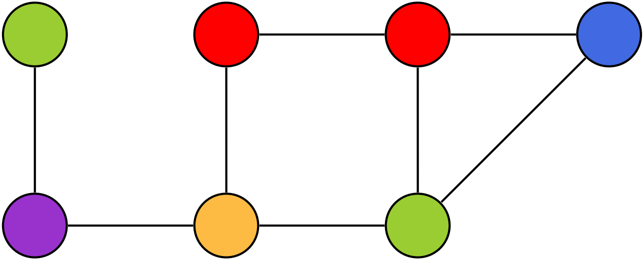
- Reading of the variables of the neighbors
- Enabled nodes
- Daemon election: models the asynchronism



Locally Shared Memory Model

Atomic Step

- Reading of the variables of the neighbors
- Enabled nodes
- Daemon election: models the asynchronism
- Update of the local states



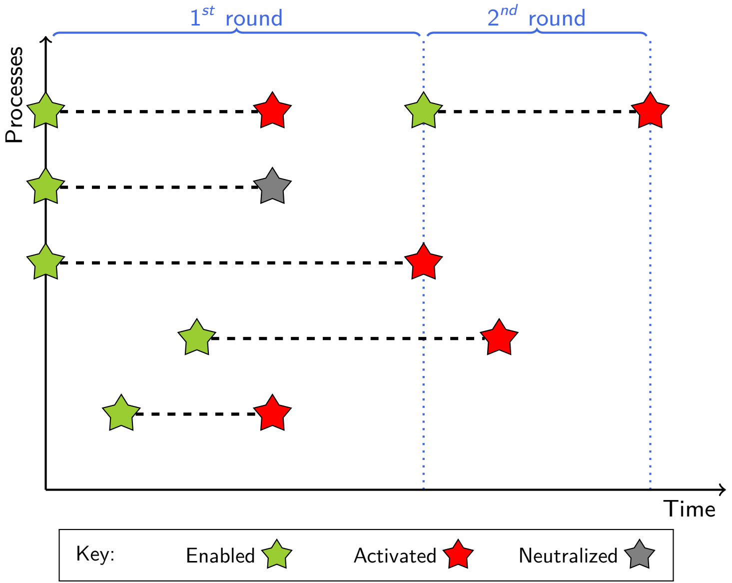
Daemons

- Synchronous
- Central / Distributed
- Fairness : Strongly Fair, Weakly Fair, Unfair

Complexity

- In space : memory requirement in bits
- In time (mainly stabilization time)
  - In (atomic) steps
  - In rounds (execution time according slowest processes)

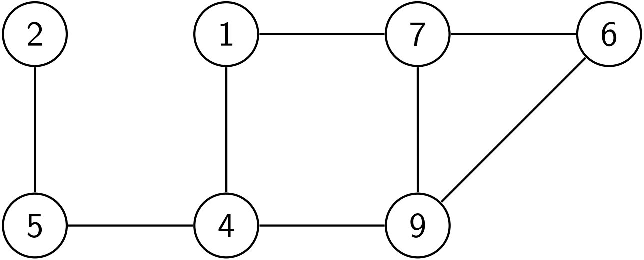
Rounds



1st round
2nd round
Processes
Time
Key:
Enabled
Activated
Neutralized

Leader Election

- Distinguish a process: the **leader**



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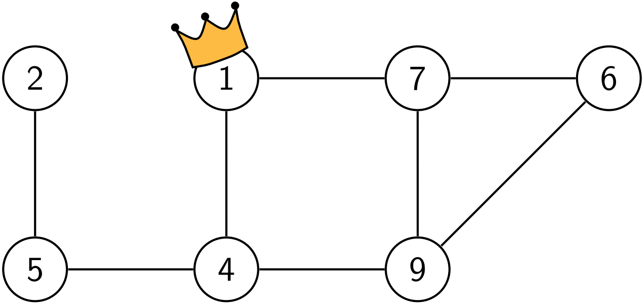
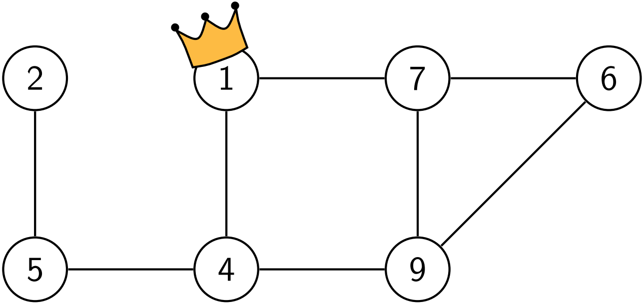


Leader Election

- Distinguish a process: the **leader**
- Every process eventually knows the identifier of the leader



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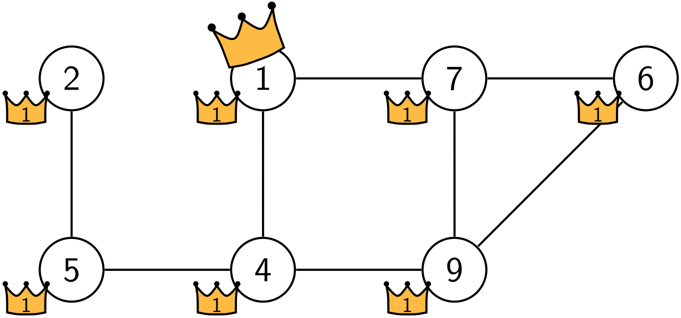

Problem

- **Silent Self-stabilizing Leader Election**
- Model:
  - **Locally shared memory** model
  - Read/write atomicity
  - Distributed **unfair** daemon
- Network:
  - Any connected topology
  - Bidirectional
  - **Identified**
- **No global knowledge** on the network

State of the Art

Model	Paper	Knowledge			Daemon	Complexity			Silent
		D	N	B		Memory	Rounds	Steps	
Message Passing	Afek, Bremler, 1998			x		$\Theta(\log n)$	$O(n)$	?	✓
	Awerbuch *et al*, 1993	x				$\Theta(\log D \log n)$	$O(\mathcal{D})$	?	✓
	Burman, Kutten, 2007	x				$\Theta(\log D \log n)$	$O(\mathcal{D})$	?	✓
Locally Shared Memory	Dolev, Herman, 1997		x		Fair	$\Theta(N \log N)$	$O(\mathcal{D})$	?	
	Arora, Gouda, 1994	x			Weakly Fair	$\Theta(\log N)$	$O(N)$	?	✓
	Datta *et al*, 2010				Unfair	unbounded	$O(n)$	?	✓
	Kravchik, Kutten, 2013				Synchronous	$\Theta(\log n)$	$O(\mathcal{D})$	?	✓
	Datta *et al*, 2011				Unfair	$\Theta(\log n)$	$O(n)$	?	✓

$\mathcal{D}$: Diameter
$D \geq \mathcal{D}$: Upper bound on the diameter

n: Number of nodes
$N \geq n$: Upper bound on the number of nodes

B: Upper bound on the link-capacity

Our Contribution

Algorithm $\mathcal{LE}$

- Memory requirement asymptotically optimal: $\Theta(\log n)$ bits/process
- Stabilization time (worst case):
  - $3n + \mathcal{D}$ rounds
  - Lower Bound: $\frac{n^3}{6} + \frac{3}{2}n^2 - \frac{8}{3}n + 2$ steps,
    Upper Bound: $\frac{n^3}{2} + 2n^2 + \frac{n}{2} + 1$ steps

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Analytical Study of Datta *et al*, 2011[3]

- Stabilization time not polynomial in steps:
  - $\forall \alpha \geq 3$, $\exists$ networks and executions in $\Omega(n^{\alpha+1})$ steps.

[3] Datta, Larmore, and Vemula. Self-stabilizing Leader Election in Optimal Space under an Arbitrary Scheduler. 2011

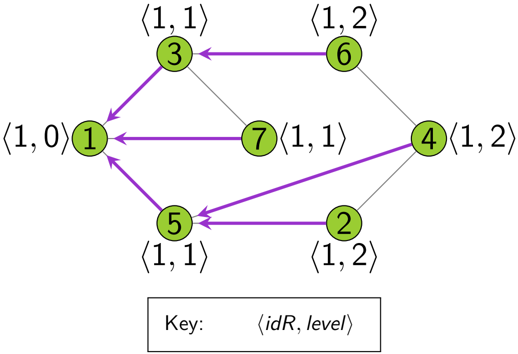
Design of the Leader Election Algorithm

Simplified Algorithm (Non Self-stabilizing)

Join a Tree

3 variables per process p

- $p.idR \in \mathbb{N}$: ID of the root
- $p.par \in \mathcal{N}_p \cup \{p\}$: Parent pointer
- $p.level \in \mathbb{N}$: Level



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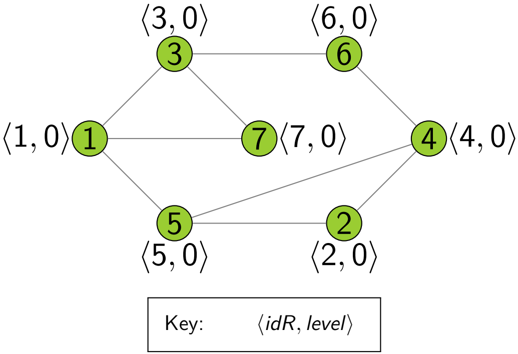

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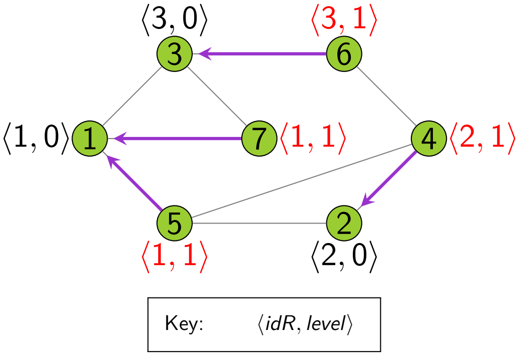

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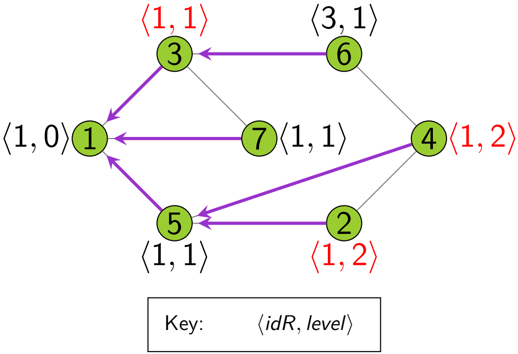

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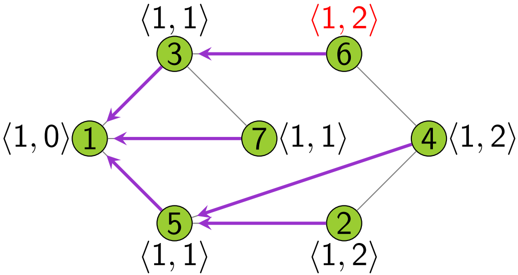
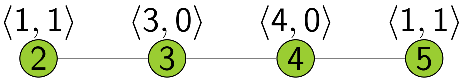


Key: $\langle idR, level \rangle$

Simplified Algorithm (Non Self-Stabilizing)

Self-stabilization $\Longrightarrow$ Arbitrary initialization



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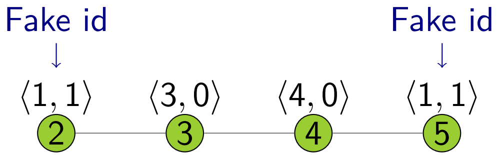
Simplified Algorithm (Non Self-Stabilizing)

Self-stabilization $\Longrightarrow$ Arbitrary initialization $\Longrightarrow$ Fake ids



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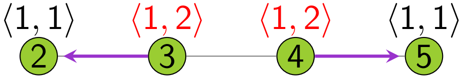

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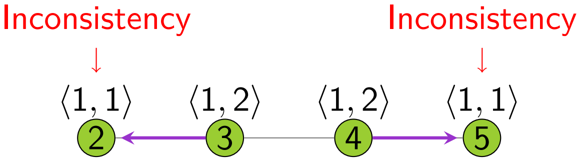
Simplified Algorithm: Removal of Fake Ids

Reset



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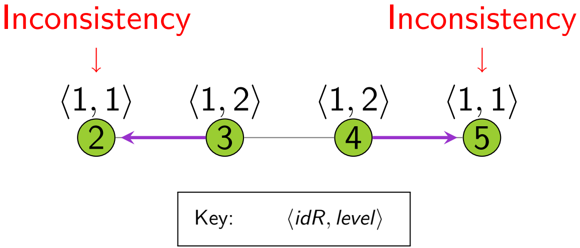

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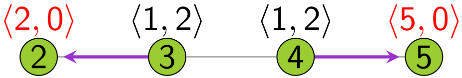

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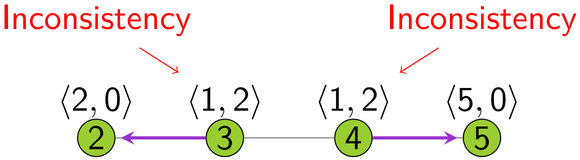

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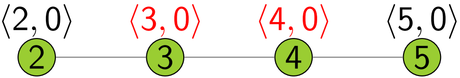

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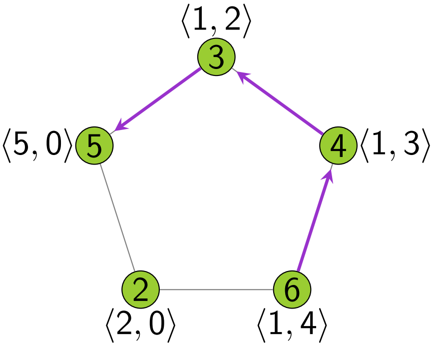

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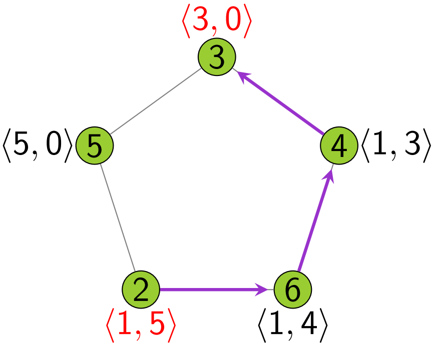

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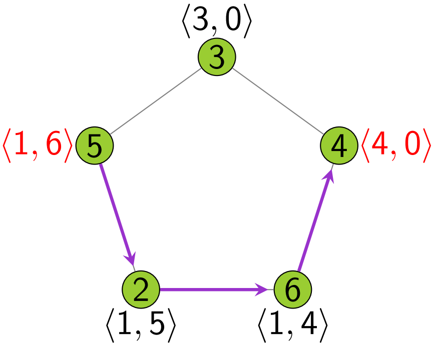

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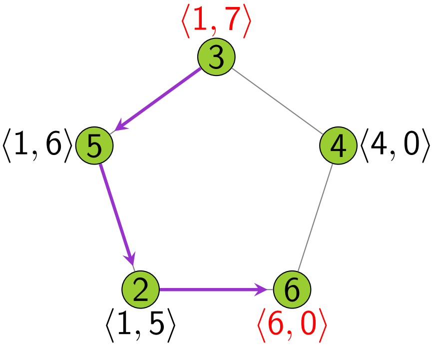

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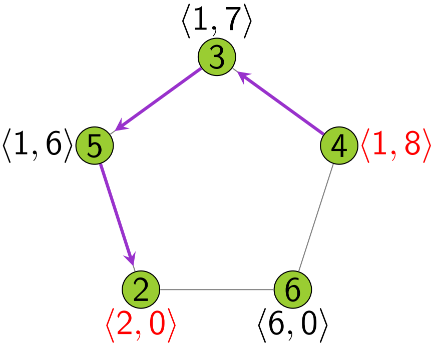

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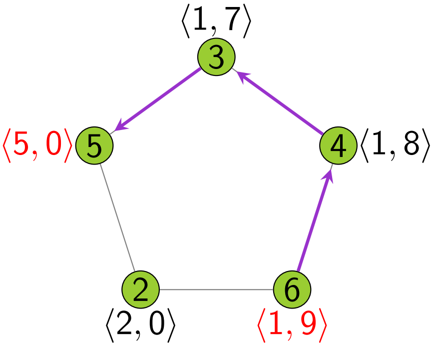

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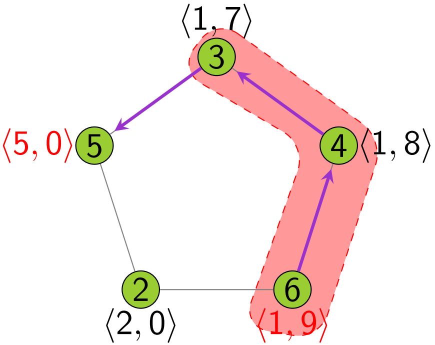

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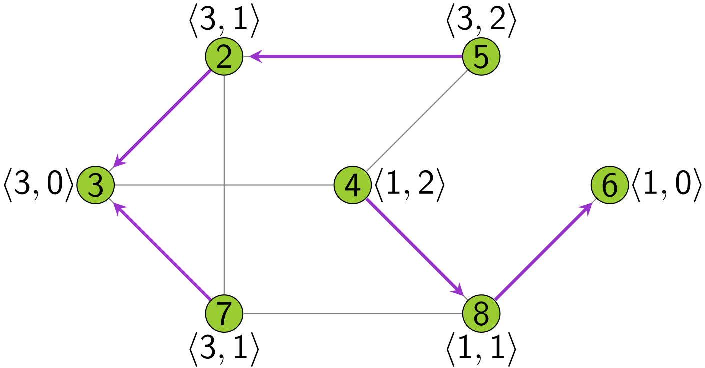
Abnormal Trees



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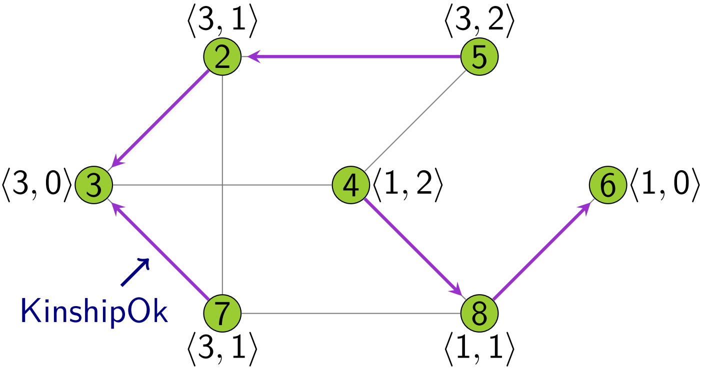

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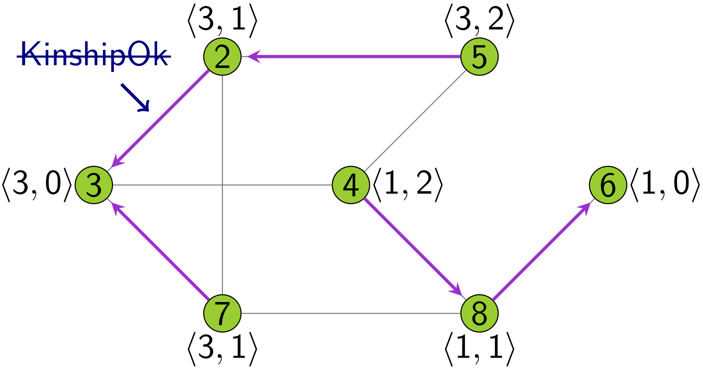

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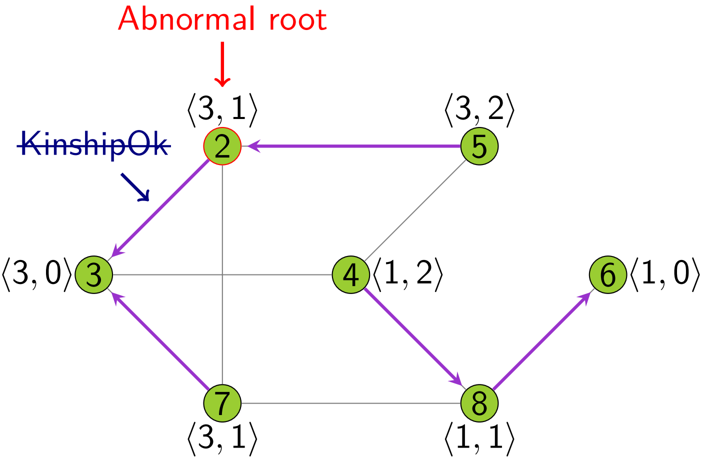

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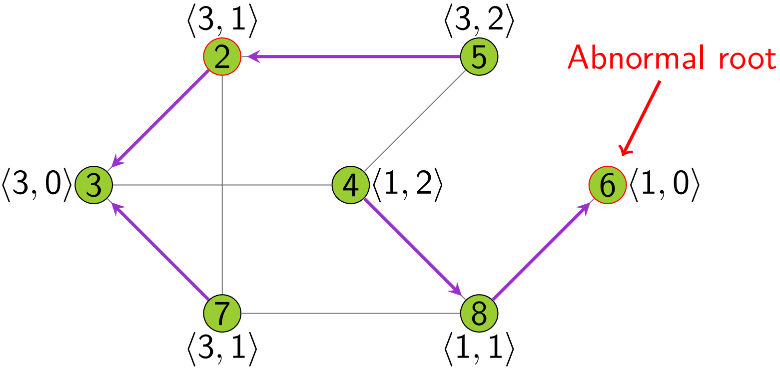

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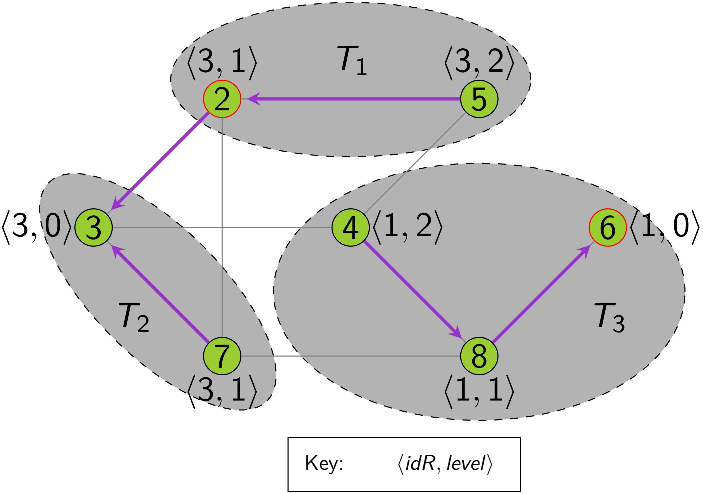

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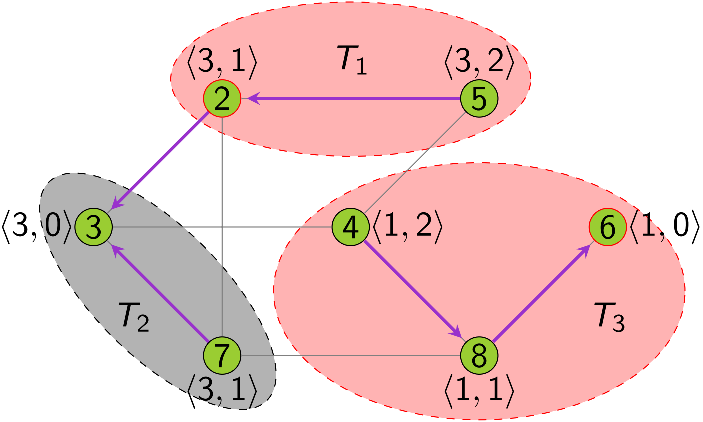

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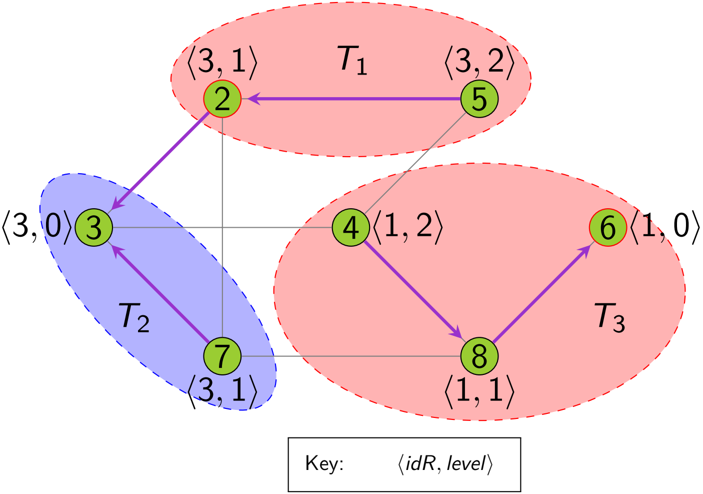

Abnormal trees removal

Freeze before Remove

Add a variable $Status \in \{C, EB, EF\}$

- C means "not involved in a tree removal":
  - Only process of status C can join a tree and
  - only by choosing a process of status C as parent
- EB: Error Broadcast
- EF: Error Feedback

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KinshipOk should be modified to take possible inconsistencies of variables *Status* into account!

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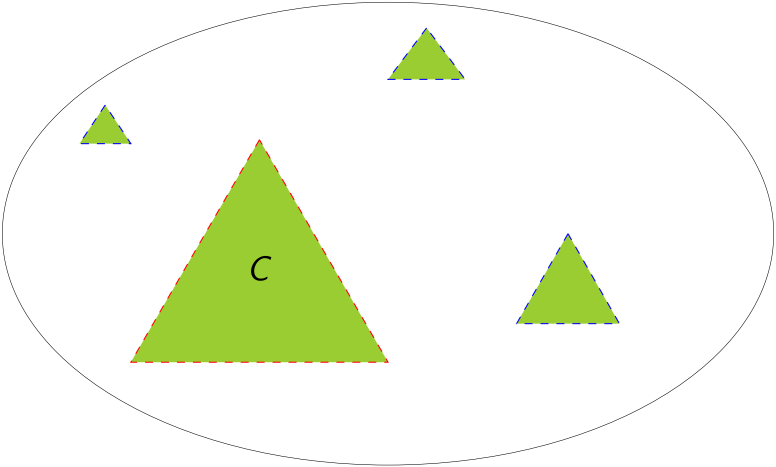
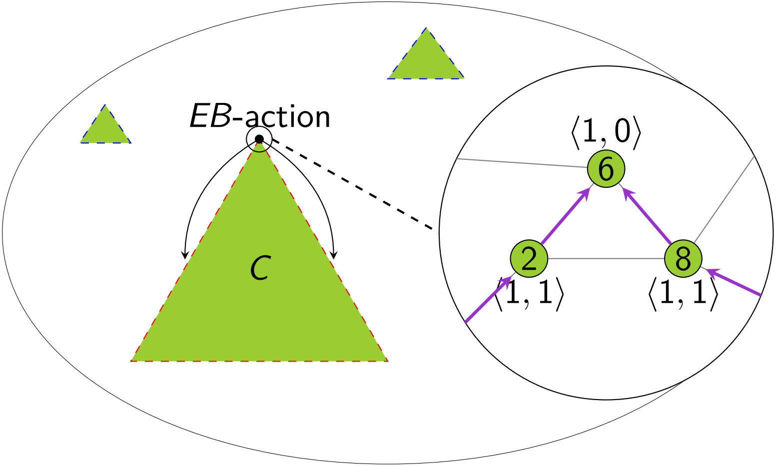


Key: $\langle idR, level \rangle$ $Clean$ $EBroadcast$ $EFeedback$

Freeze before remove



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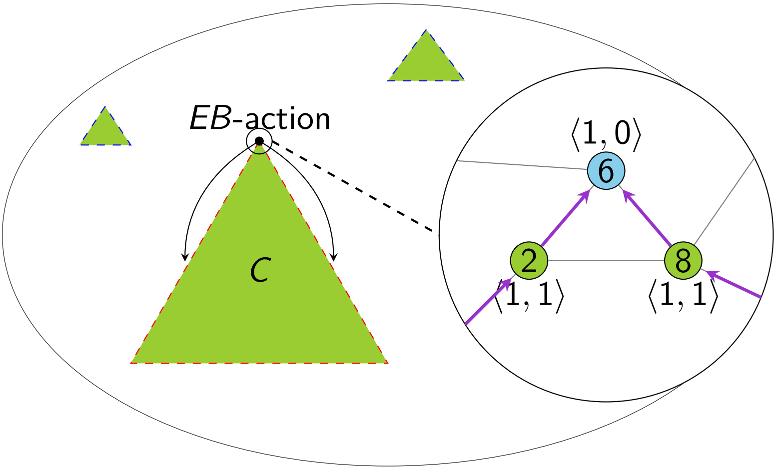

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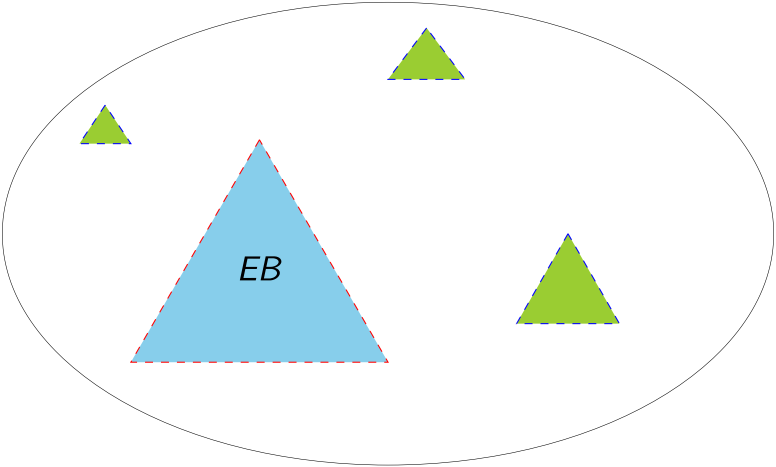

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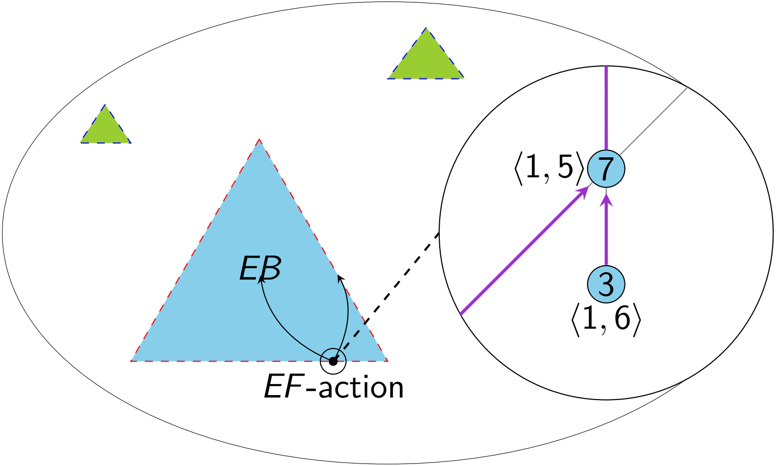

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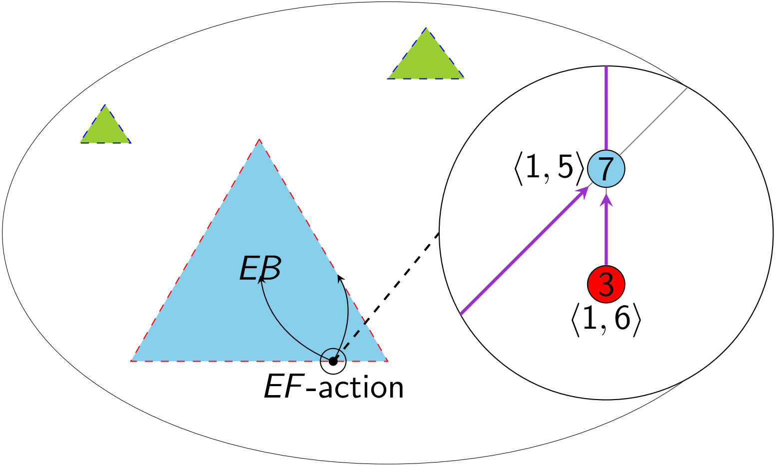

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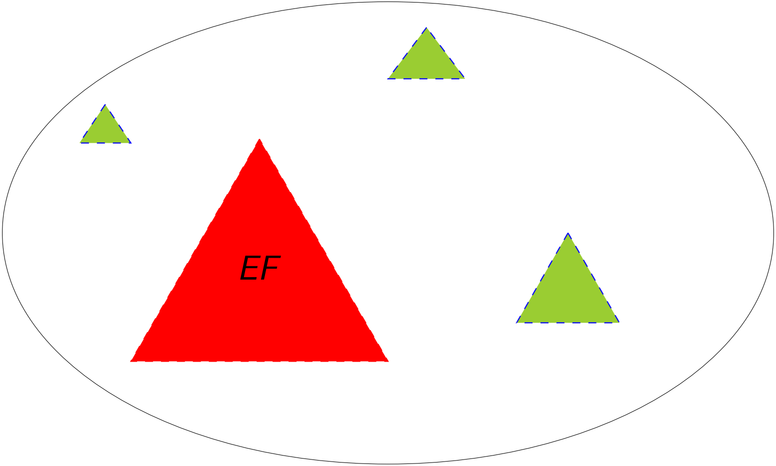
Freeze before remove



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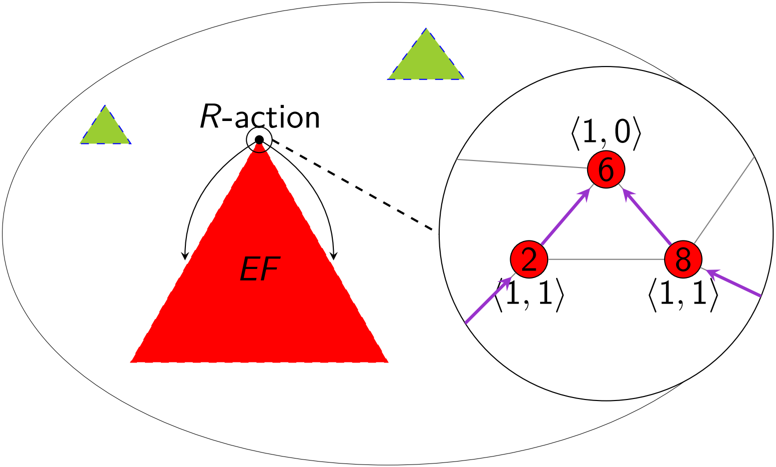

Key: ⟨*idR*, *level*⟩ *Clean* *EBroadcast* *EFeedback*

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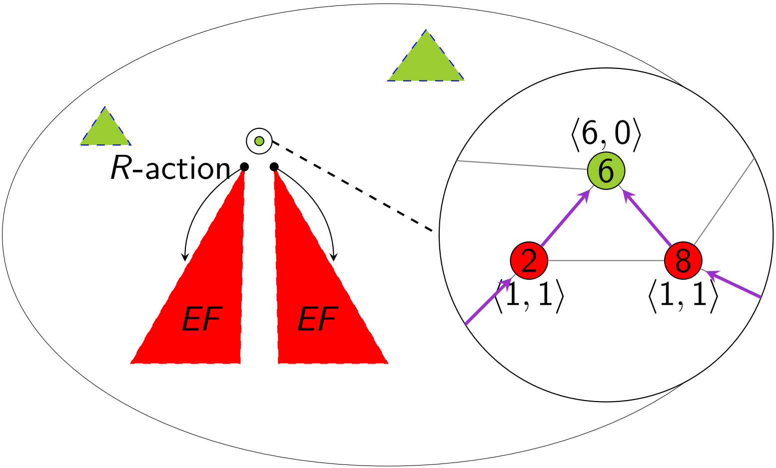

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Stabilization Time in Rounds

- No alive abnormal tree created
- Height of an abnormal tree: at most n

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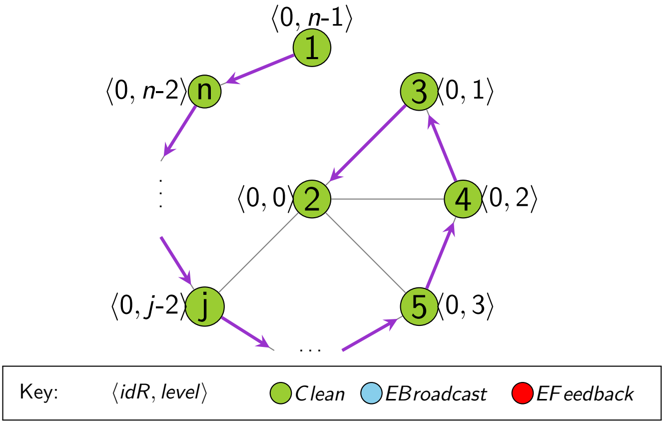
$O(3n + \mathcal{D})$ **rounds**

Lower Bound on the Worst Case Stabilization Time in Rounds (synchronous execution)

- k links
- $j = k + 3$
- $\mathcal{D} = n - k$



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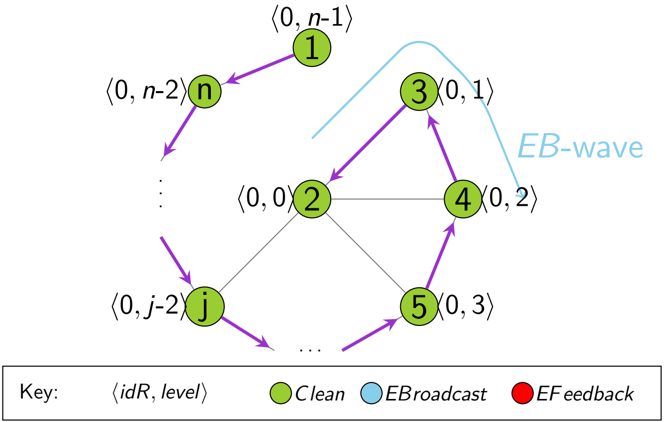

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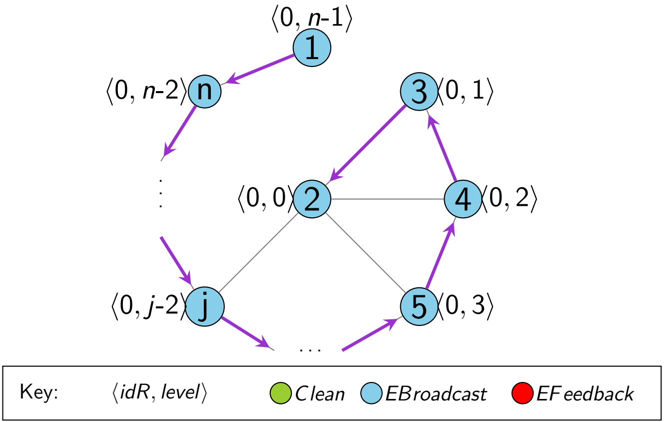
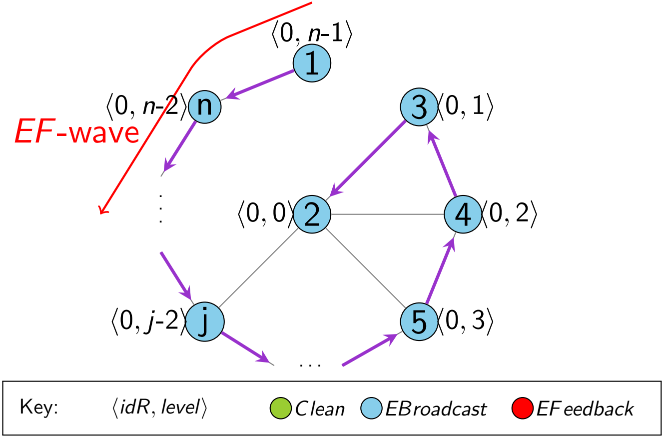


n

Lower Bound on the Worst Case Stabilization Time in Rounds (synchronous execution)

- k links
- $j = k + 3$
- $\mathcal{D} = n - k$



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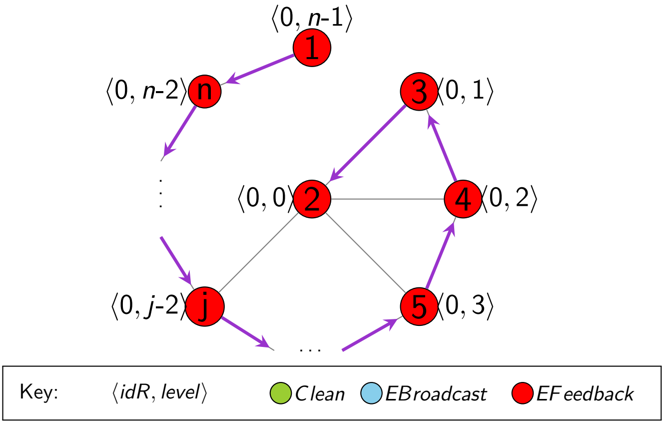

$n + n$

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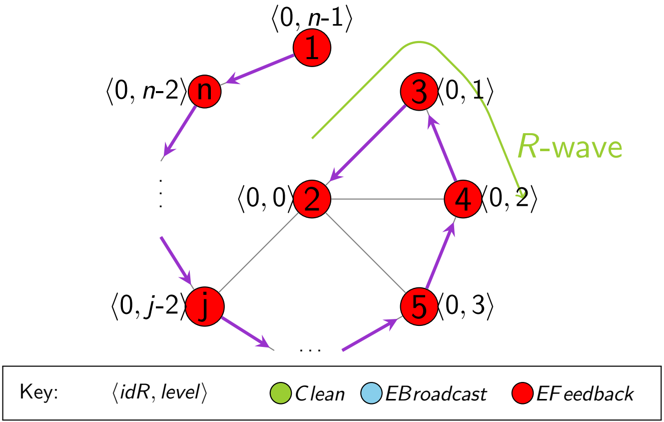

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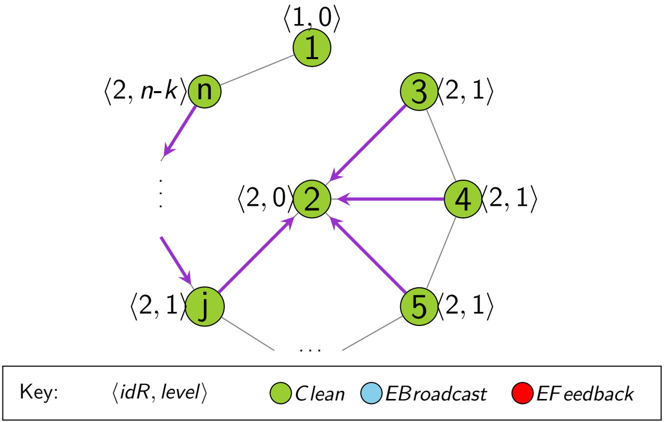

$n + n + n$

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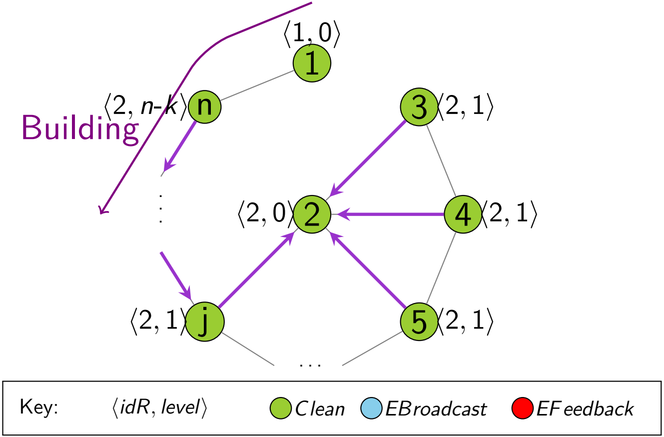

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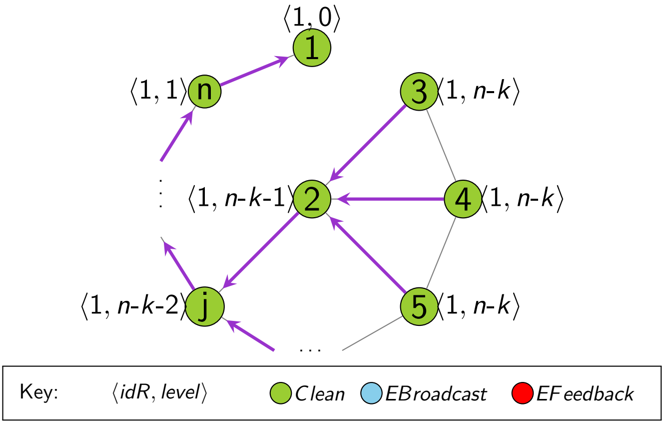

$n + n + n + (n - k)$

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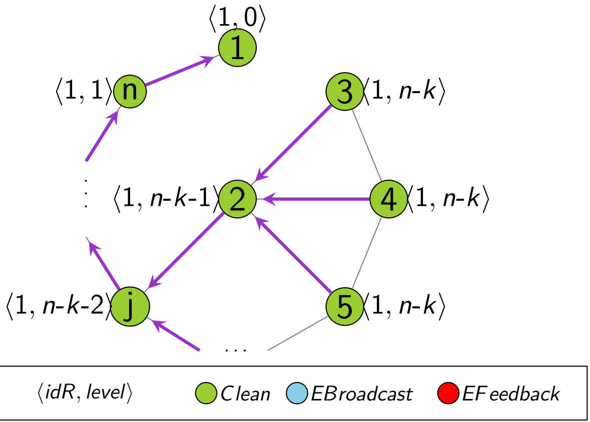
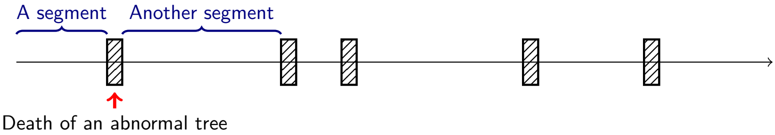


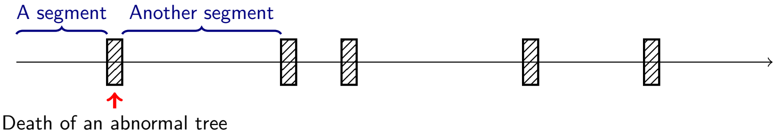
$$n + n + n + (n - k)$$

$$= \text{exactly } 3n + \mathcal{D} \text{ rounds}$$

Stabilization Time in Steps

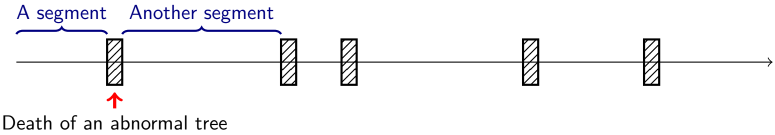


Stabilization Time in Steps



At most *n* alive abnormal trees + No alive abnormal tree created

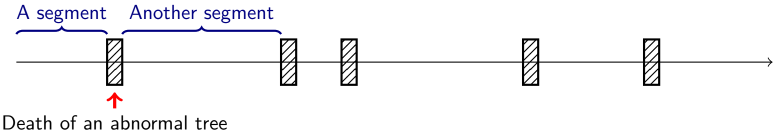
Stabilization Time in Steps



At most n alive abnormal trees $+$ No alive abnormal tree created

$\longrightarrow$ At most $n+1$ segments

Stabilization Time in Steps



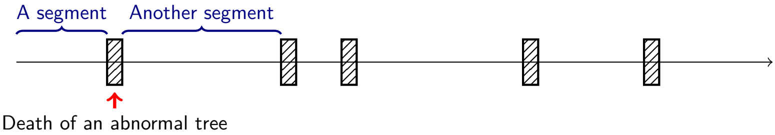
At most n alive abnormal trees $+$ No alive abnormal tree created

$\longrightarrow$ At most $n+1$ segments

In a segment

$$idR : 7 \xrightarrow{J\text{-action}} 5 \xrightarrow{J\text{-action}} 3 \xrightarrow{J\text{-action}} 2 \underbrace{\xrightarrow{EB\text{-action}} \xrightarrow{EF\text{-action}} \xrightarrow{R\text{-action}}}_{\text{Death of an abnormal tree = End of the segment}} 7 \xrightarrow{J\text{-action}} 3$$

Stabilization Time in Steps



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- $n-1$ J-actions
- 1 EB-action
- 1 EF-action
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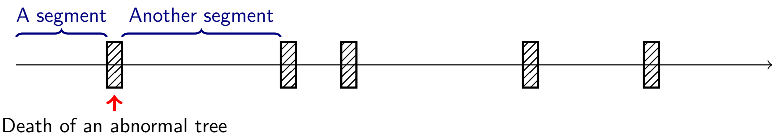
Stabilization Time in Steps



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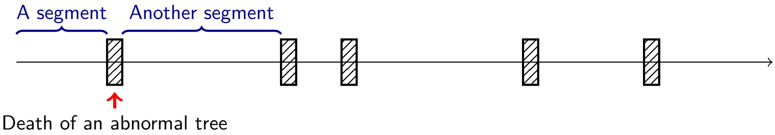
$\Rightarrow O(n)$ actions per process

Stabilization Time in Steps



At most n alive abnormal trees + No alive abnormal tree created

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In a segment

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Death of an abnormal tree = End of the segment

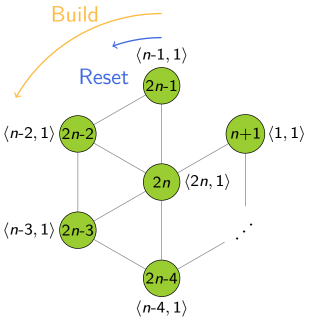
- $n-1$ J-actions
- 1 EB-action
- 1 EF-action
- 1 R-action

$\Rightarrow O(n)$ actions per process

$O(n^3)$ steps

Lower Bound: $\frac{n^3}{6} + \frac{3}{2}n^2 - \frac{8}{3}n + 2$ steps Upper Bound: $\frac{n^3}{2} + 2n^2 + \frac{n}{2} + 1$ steps

Lower Bound on the Worst Case Stabilization Time in Steps



Key: $\langle idR, level \rangle$

Clean *EBroadcast* *EFeedback*

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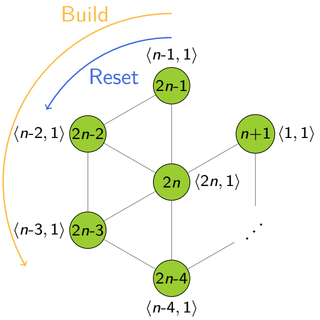

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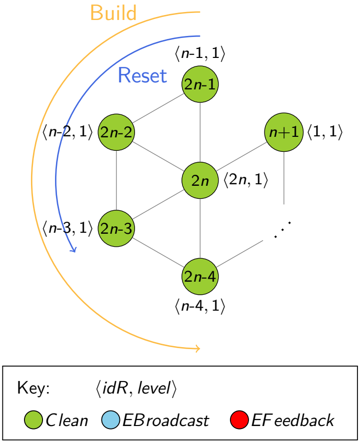

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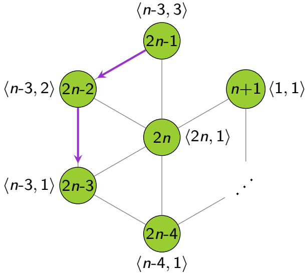

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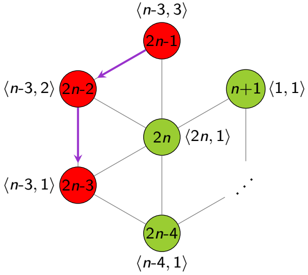

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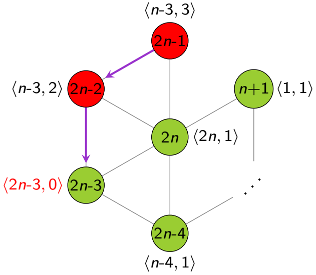

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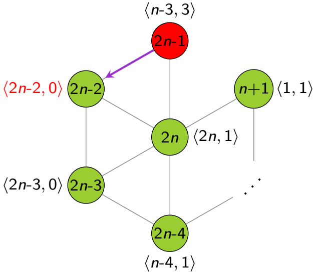

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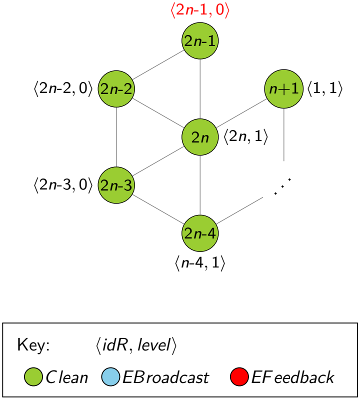

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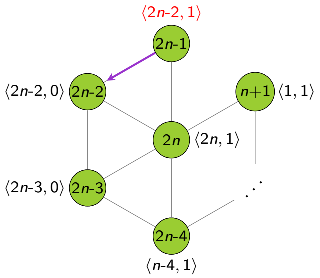
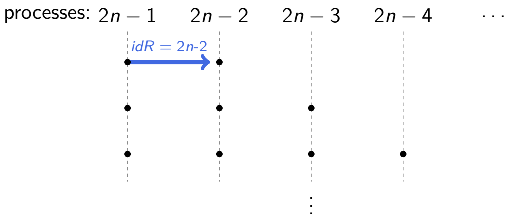


Key: $\langle idR, level \rangle$

Clean EBroadcast EFeedback

Case of the reset of $2n-4$



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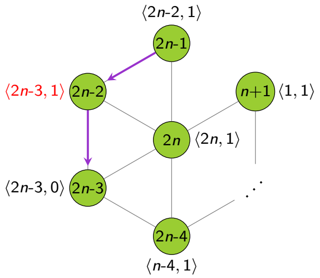

Key: ⟨*idR*, *level*⟩

Clean *EBroadcast* *EFeedback*

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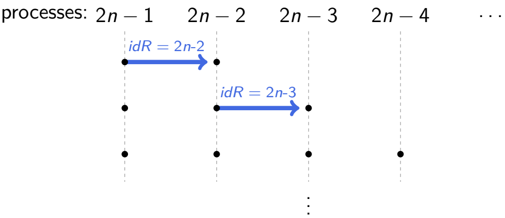

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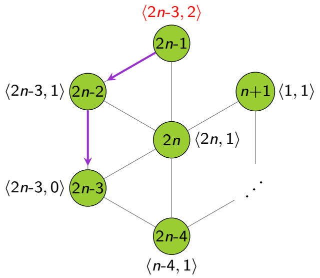

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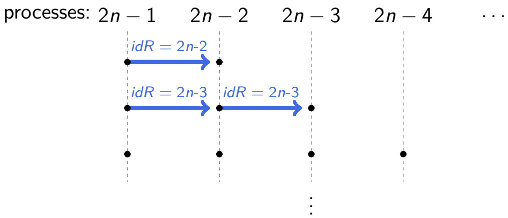

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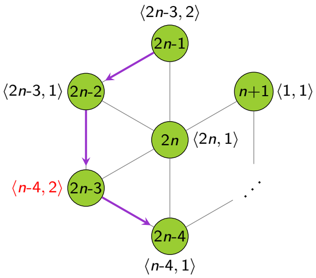

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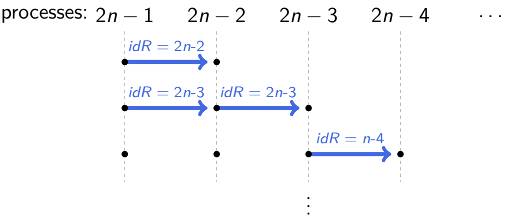

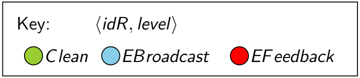

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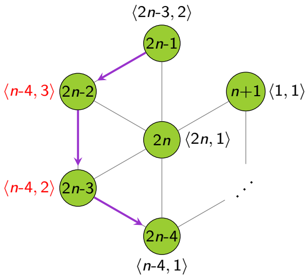

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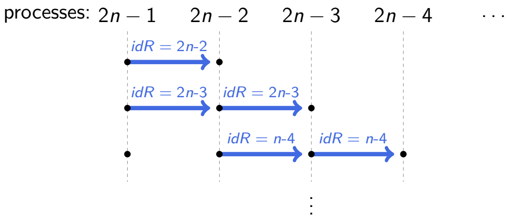

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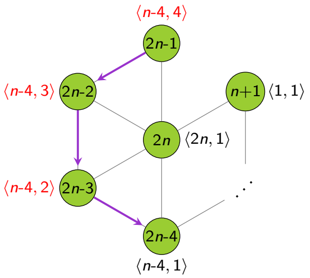

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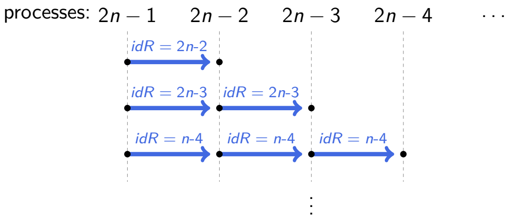

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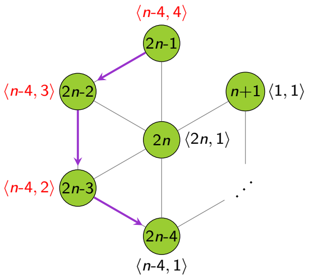

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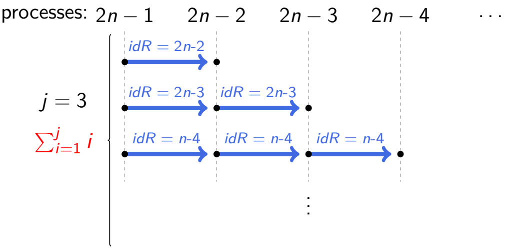

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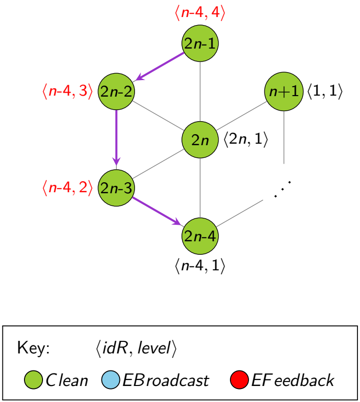

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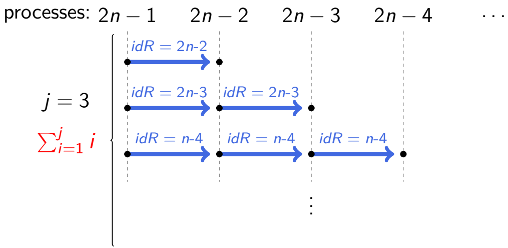


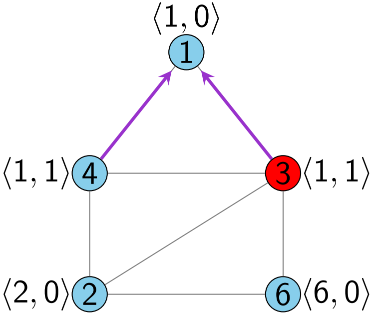
$$\Theta(n) \text{ reset } \Rightarrow \sum_{j=1}^{n} \sum_{i=1}^{j} i \Rightarrow \Theta(n^3) \text{ steps}$$

Analytical Study of Datta *et al*, 2011[4]

[4] Datta, Larmore, and Vemula. Self-stabilizing Leader Election in Optimal Space under an Arbitrary Scheduler. 2011

Principles

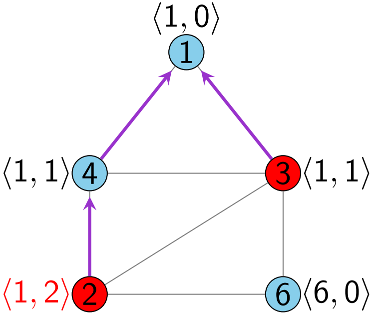
Join a tree



Key:	$\langle idR, level\rangle$	Can be joined	Cannot be joined

Principles

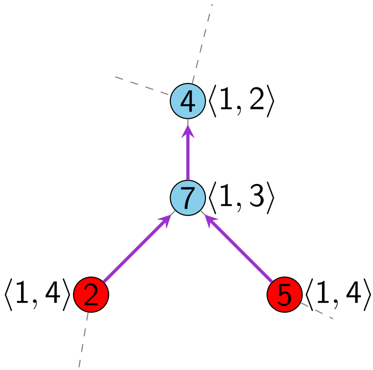
Join a tree



Key:	⟨*idR*, *level*⟩	Can be joined	Cannot be joined

Principles

Change of color



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Principles

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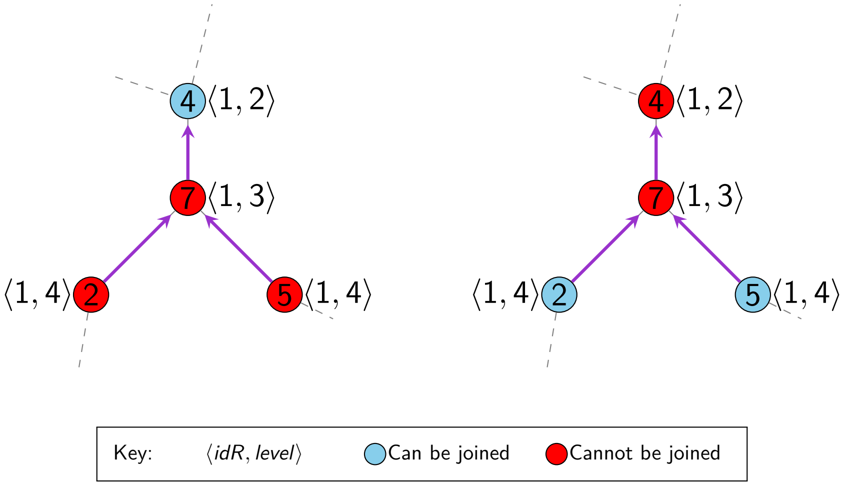

Principles

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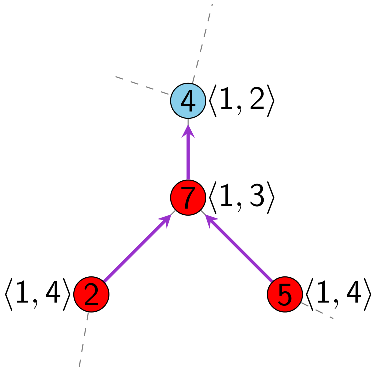
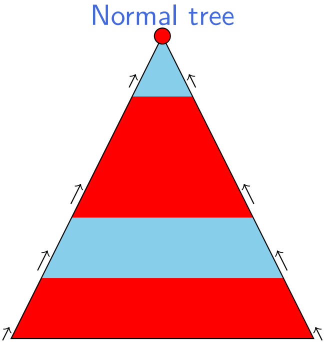


Key: ⟨*idR*, *level*⟩ Can be joined Cannot be joined

Principles

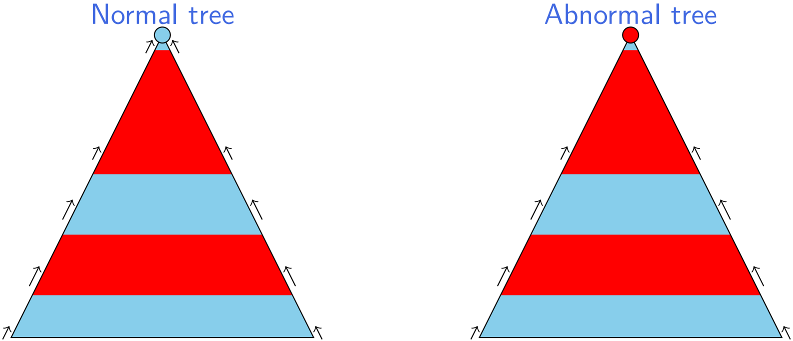
Color Waves Absorption



Key:	$\langle idR, level\rangle$	Can be joined	Cannot be joined

Principles

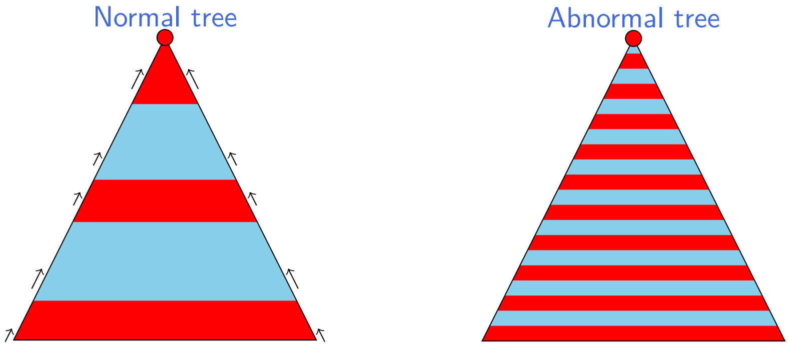
Color Waves Absorption



Key: ⟨*idR*, *level*⟩ 🔵 Can be joined 🔴 Cannot be joined

Principles

Color Waves Absorption



Key: ⟨*idR*, *level*⟩ Can be joined Cannot be joined

Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

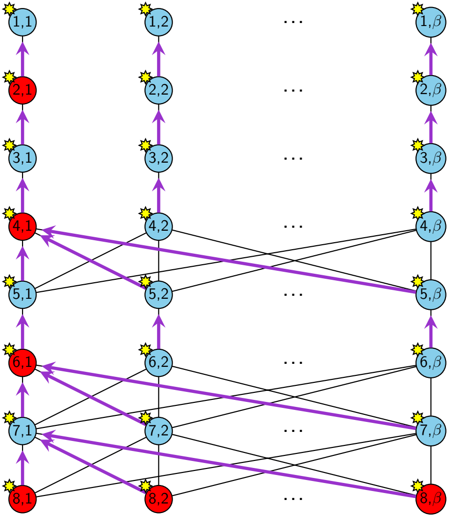
Key:

$(i,j).ID = (i-1)\beta + j$

$(i,j).idR = 0$

Can be joined

Cannot be joined



Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

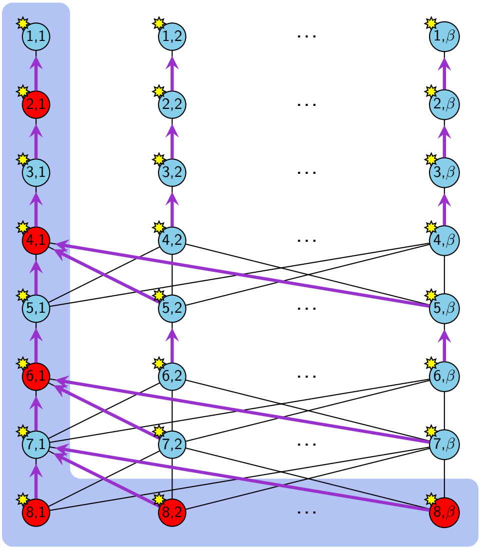
Key:

$(i, j).ID = (i-1)\beta + j$

$(i, j).idR = 0$ (star)

Can be joined (blue)

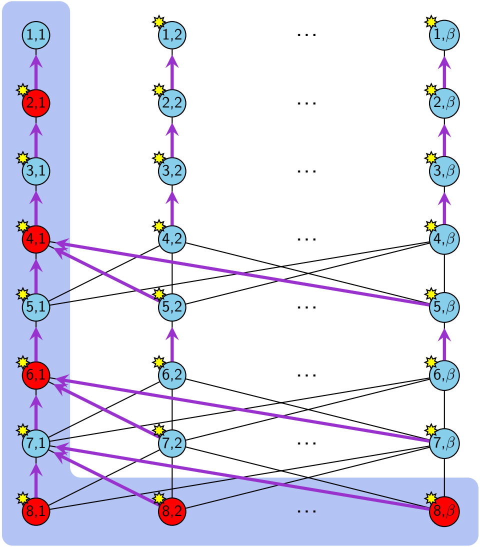
Cannot be joined (red)



Datta et al, 2011

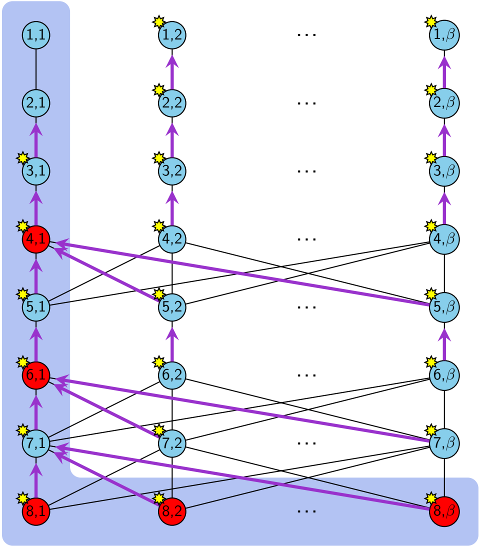
Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

Key:
$(i,j).ID = (i-1)\beta + j$
$(i,j).idR = 0$ (star)
Can be joined (blue circle)
Cannot be joined (red circle)



Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$



Key:

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Cannot be joined

Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

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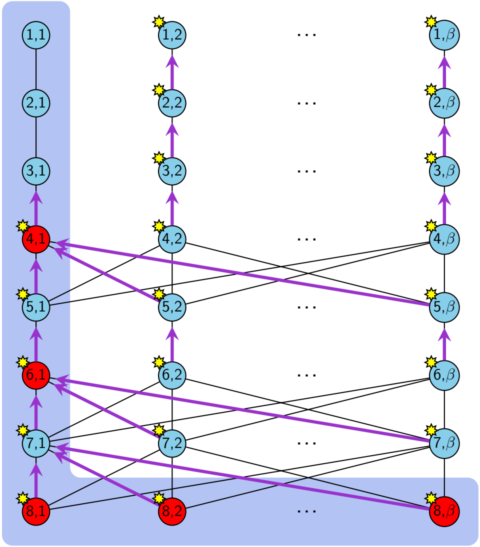
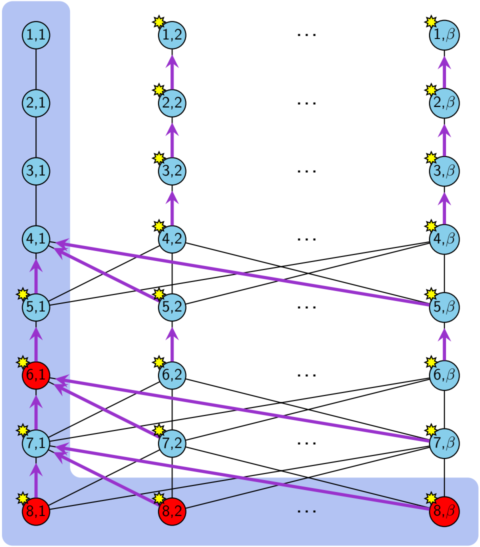


Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$



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Cannot be joined

Datta et al, 2011

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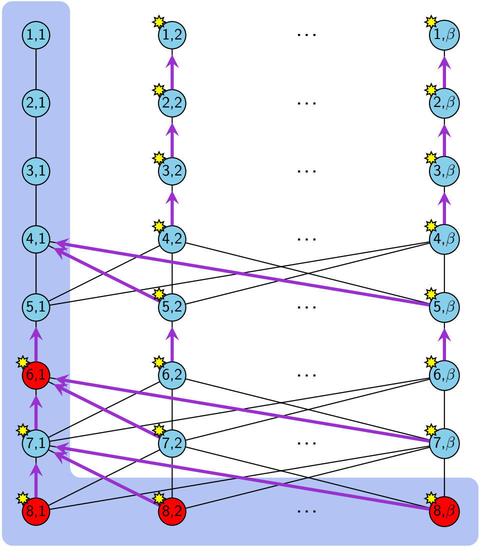

Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

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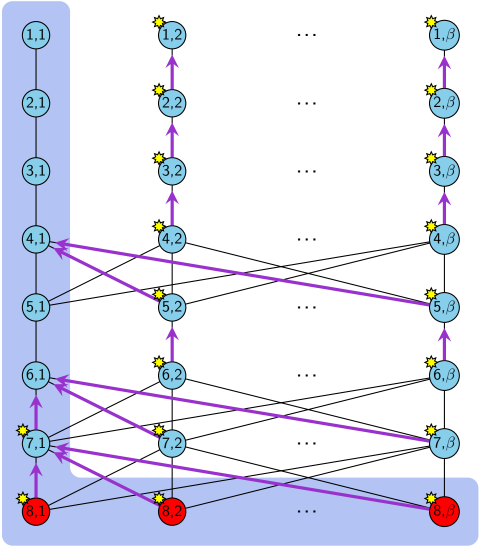

Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

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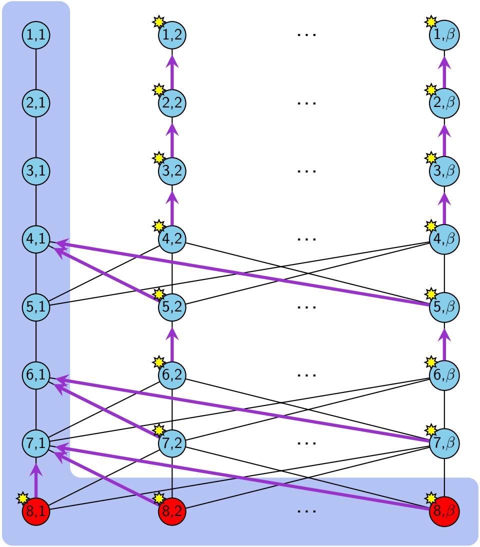

Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β

Key:

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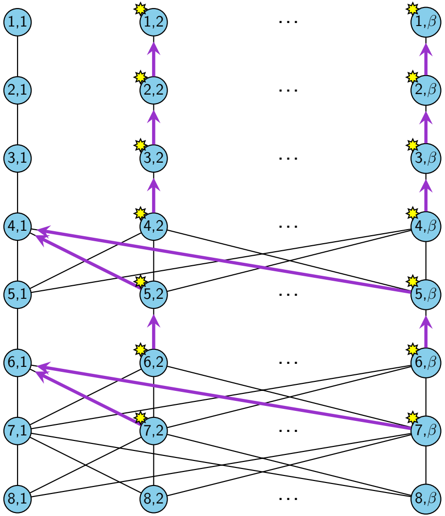
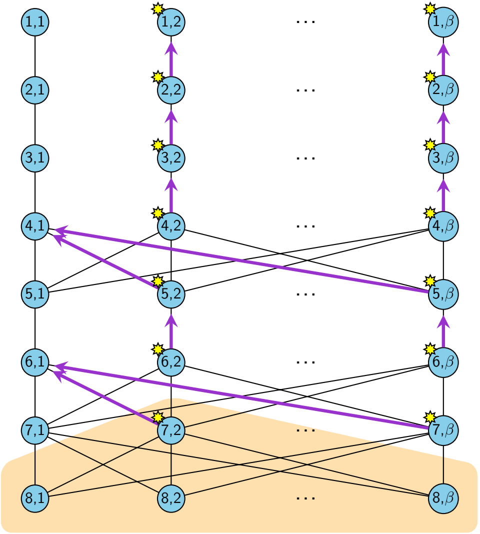


Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β



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Can be joined

Cannot be joined

Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

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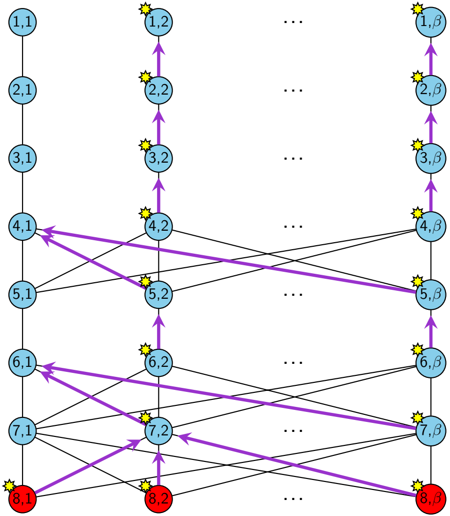

Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β

Key:
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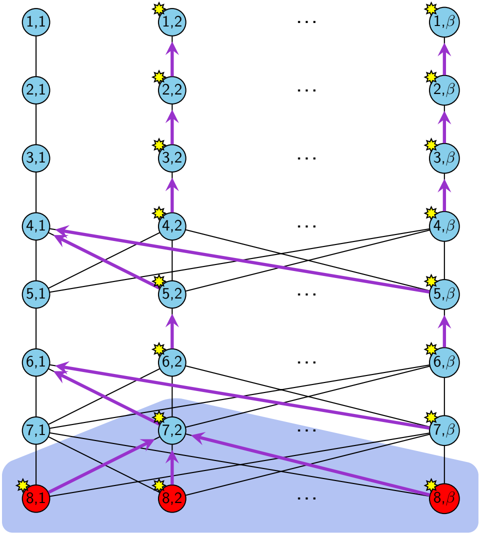
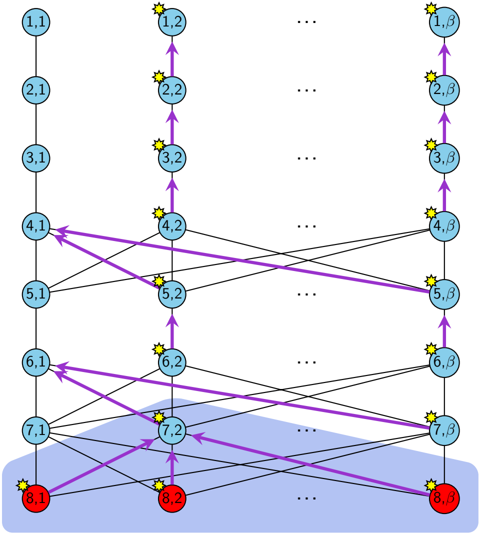
Can be joined
Cannot be joined



Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β



Key:

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Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

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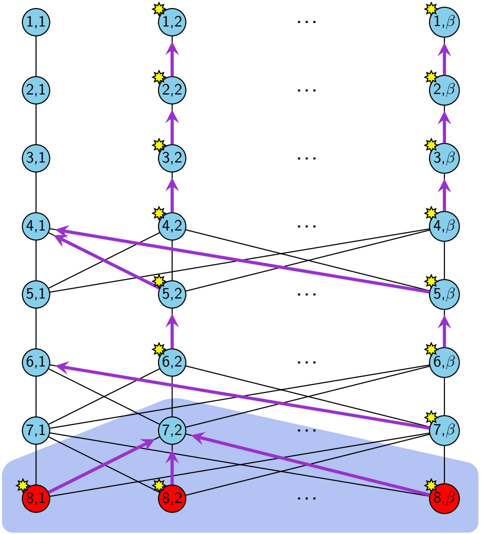

Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β

Key:

$(i,j).ID = (i-1)\beta + j$

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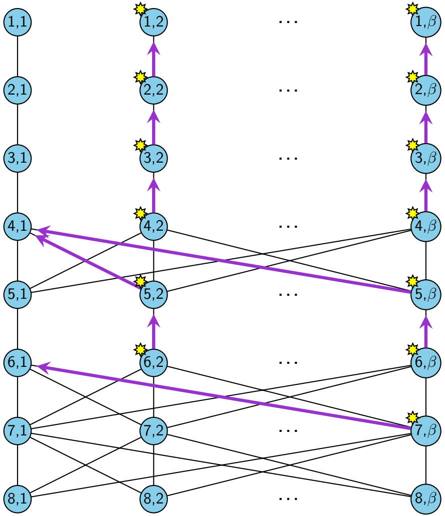
Cannot be joined



Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β

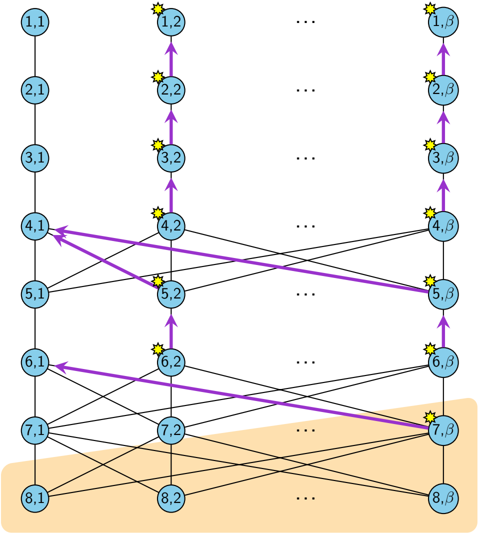
Key:

$(i,j).ID = (i-1)\beta + j$

$(i,j).idR = 0$ (star)

Can be joined (blue)

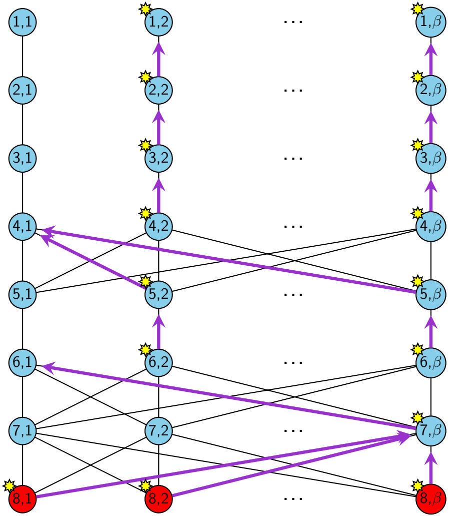
Cannot be joined (red)



Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β



Key:

$(i,j).ID = (i-1)\beta + j$

$(i,j).idR = 0$

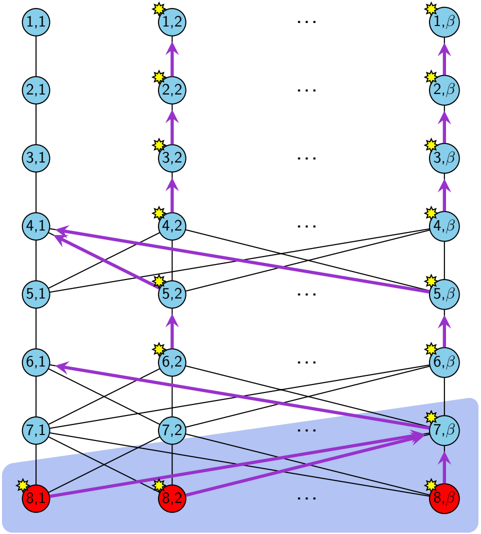
Can be joined

Cannot be joined

Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β



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● Can be joined

● Cannot be joined

Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β

Key:

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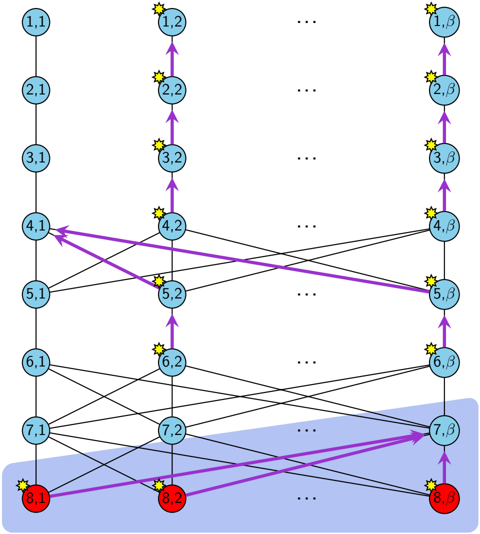
Can be joined

Cannot be joined

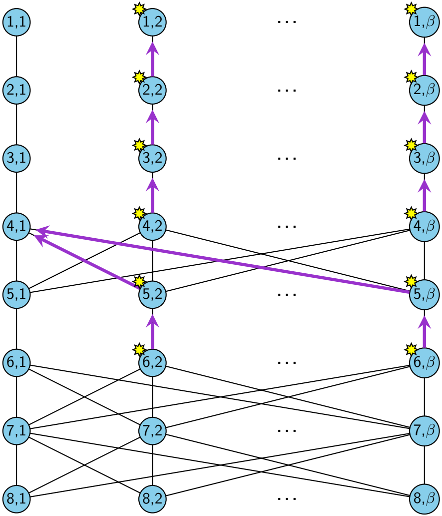


Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2

Key:
$(i,j).ID = (i-1)\beta + j$
$(i,j).idR = 0$
Can be joined
Cannot be joined

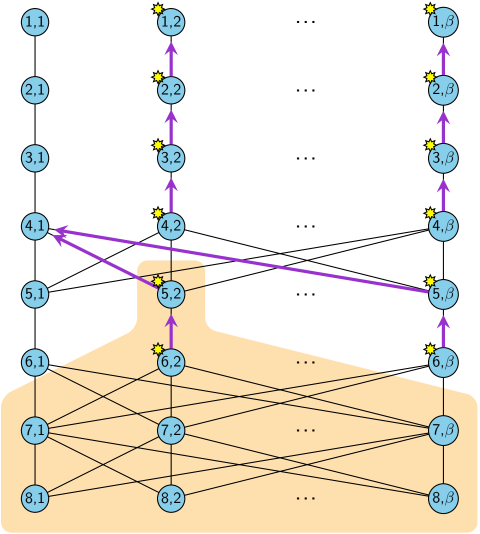


Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2

Key:
$(i, j).ID = (i-1)\beta + j$
$(i, j).idR = 0$
Can be joined
Cannot be joined



Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2

Key:

$(i,j).ID = (i-1)\beta + j$

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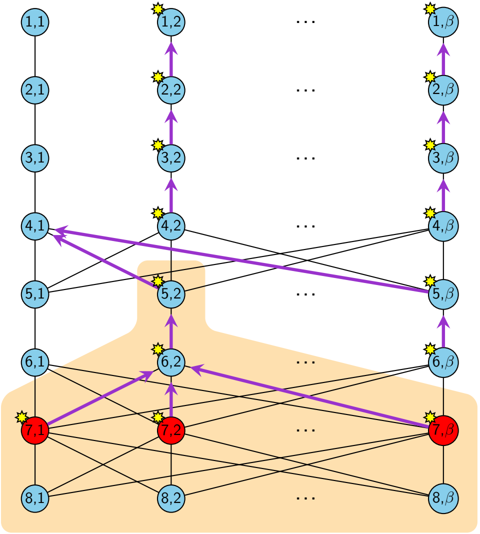
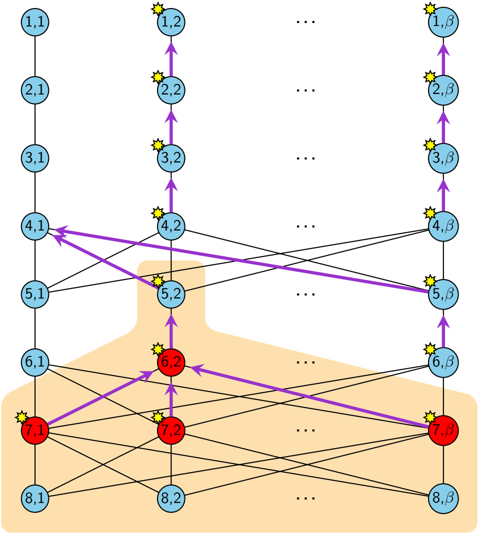


Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2



Key:
$(i,j).ID = (i-1)\beta + j$
$(i,j).idR = 0$
Can be joined
Cannot be joined

Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2

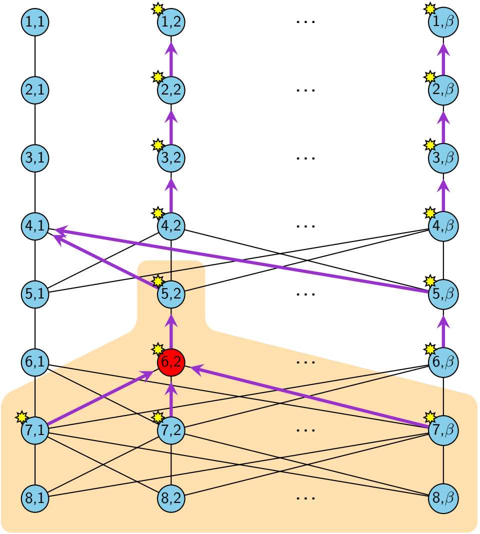
Key:

$(i,j).ID = (i-1)\beta + j$

$(i,j).idR = 0$

Can be joined

Cannot be joined



Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2

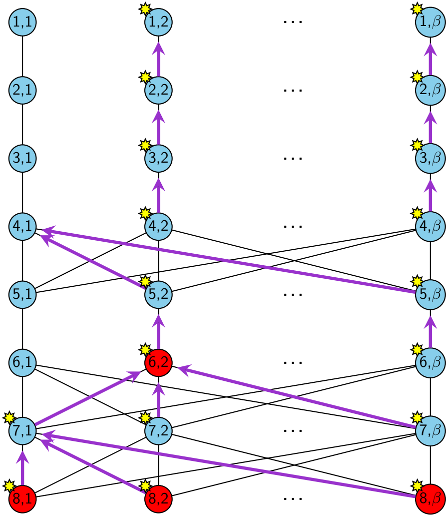
Key:

$(i,j).ID = (i-1)\beta + j$

$(i,j).idR = 0$ (star)

Can be joined (blue)

Cannot be joined (red)



Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2

Key:

$(i,j).ID = (i-1)\beta + j$

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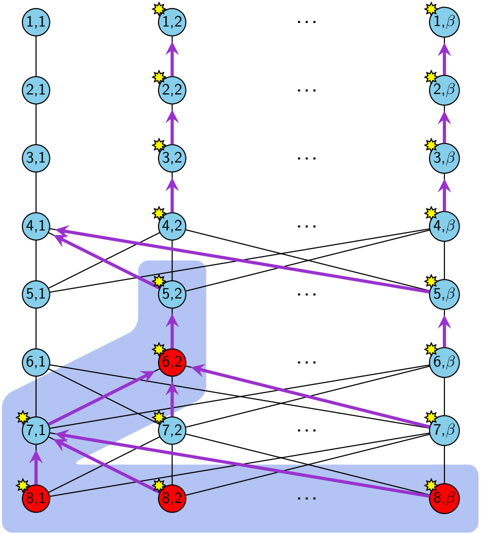
Can be joined

Cannot be joined



Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2

Key:

$(i,j).ID = (i-1)\beta + j$

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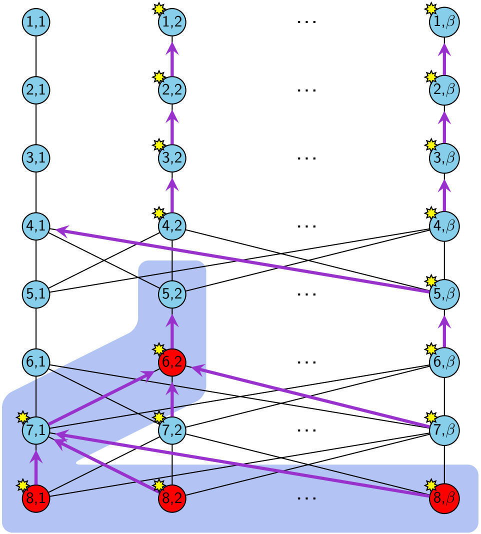
● Can be joined

● Cannot be joined



Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2

Key:

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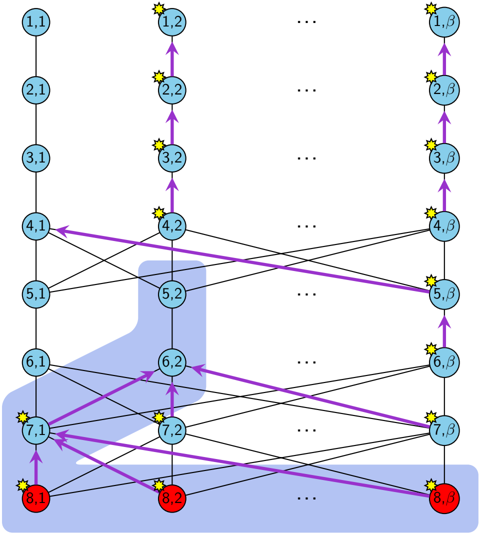
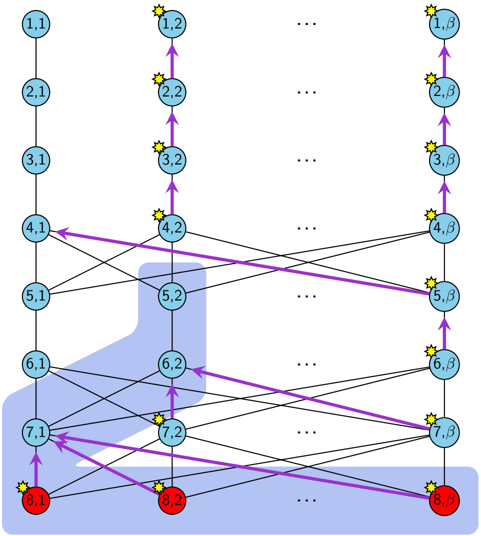


Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2



Key:

$(i,j).ID = (i-1)\beta + j$

★ $(i,j).idR = 0$

● Can be joined

● Cannot be joined

Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2

Key:
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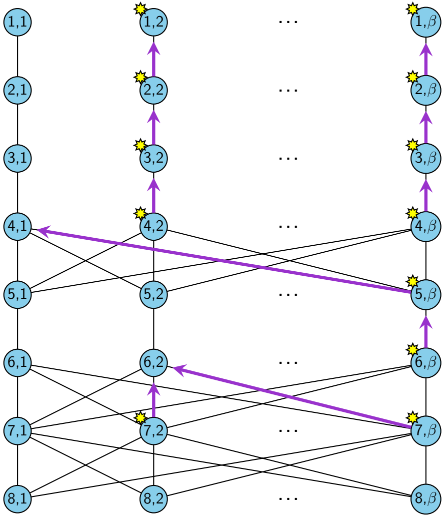
Cannot be joined



Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2

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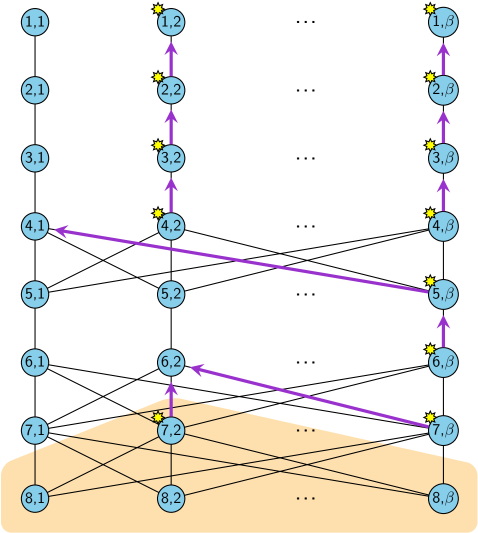

Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2

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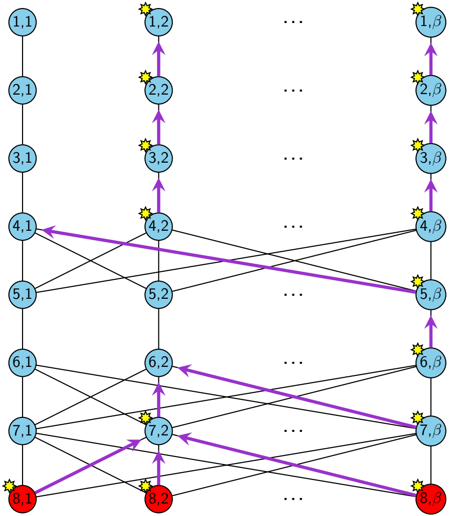

Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2

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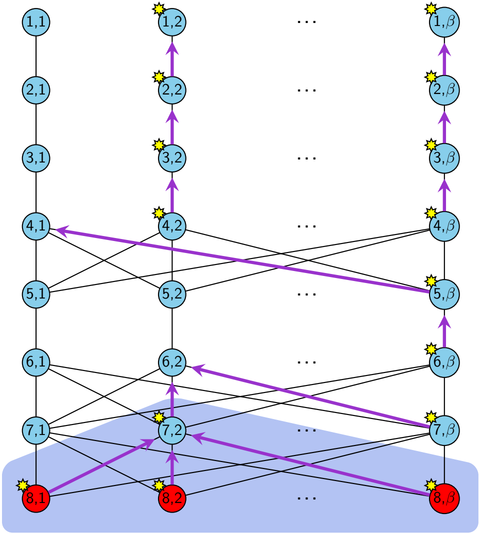
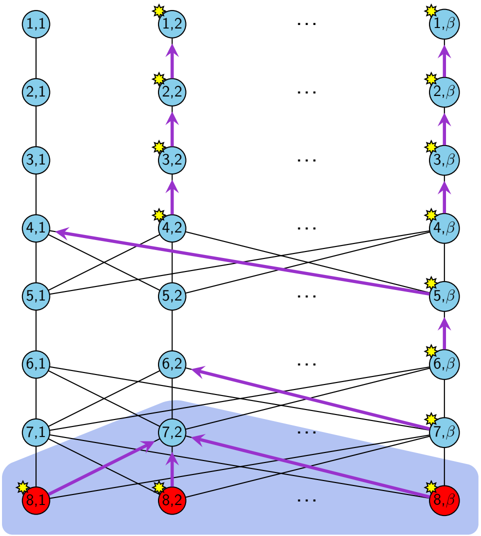


Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2



Key:

$(i,j).ID = (i-1)\beta + j$

$(i,j).idR = 0$ (marked with a star)

Can be joined (blue)

Cannot be joined (red)

Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2

Key:
$(i,j).ID = (i-1)\beta + j$
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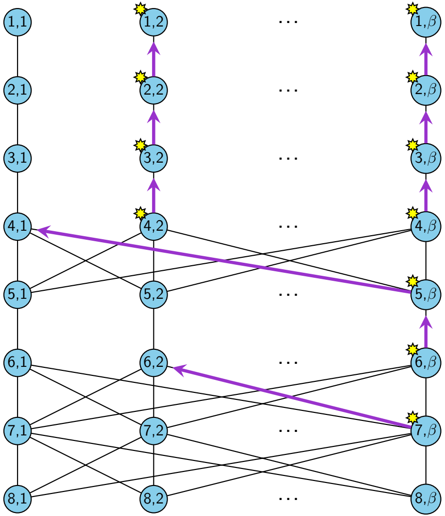
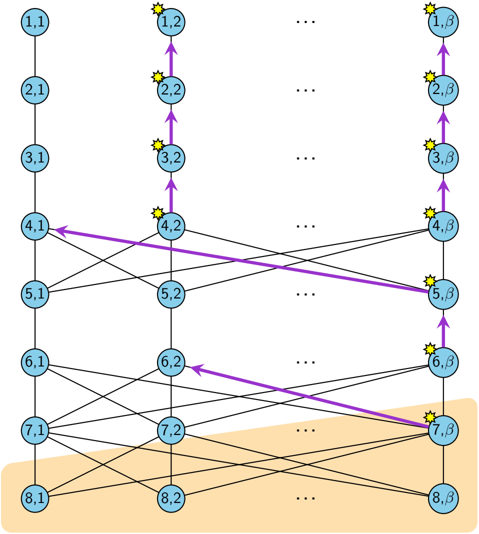
Cannot be joined



Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2



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Cannot be joined

Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2

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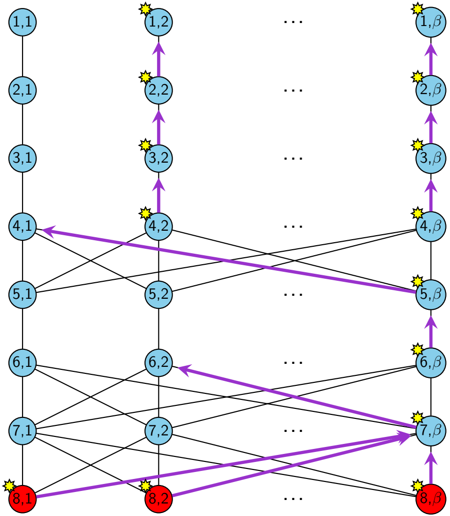
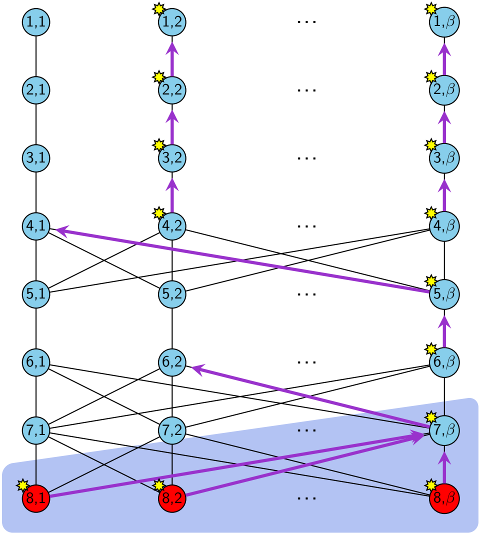


Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2



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Datta et al, 2011

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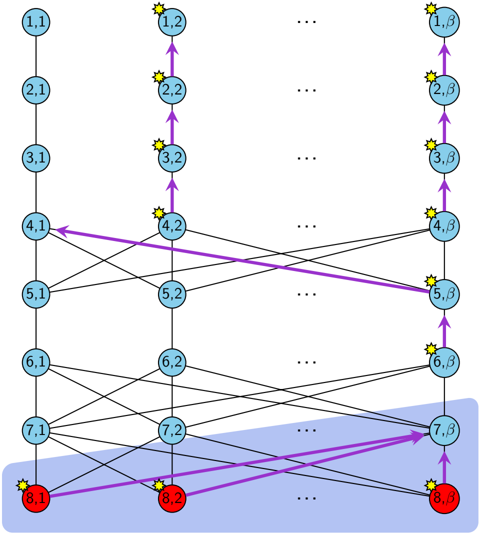
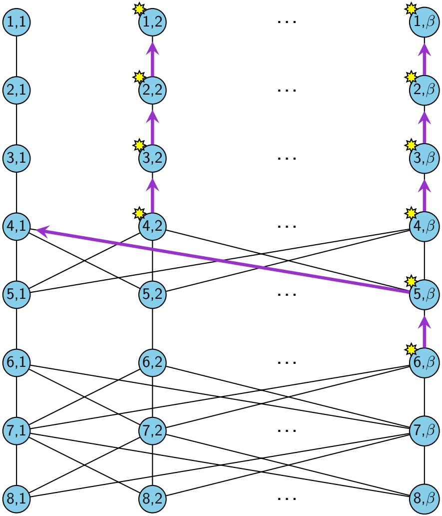


Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2

Key:
$(i,j).ID = (i-1)\beta + j$
$(i,j).idR = 0$ (star)
Can be joined (blue)
Cannot be joined (red)



Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2

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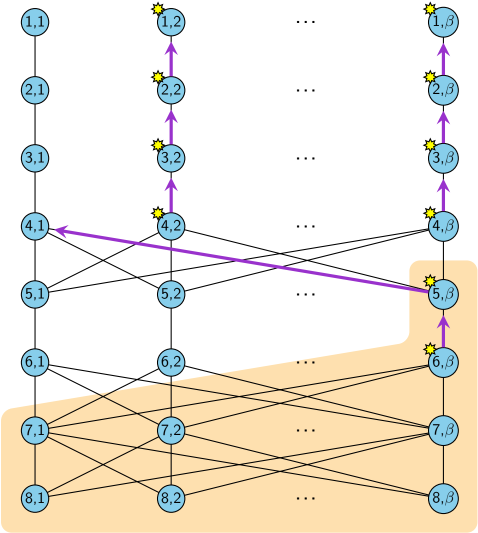


Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2

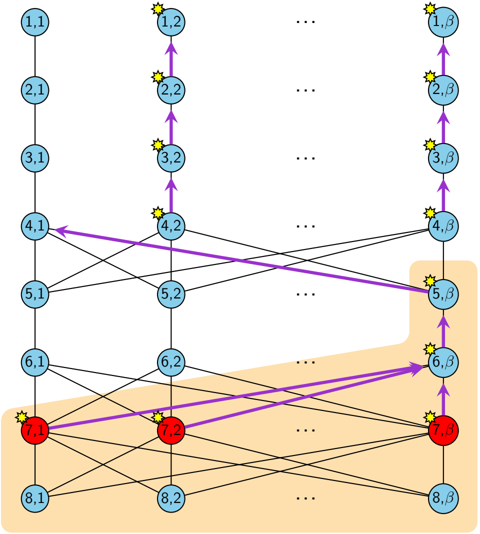
Key:

$(i,j).ID = (i-1)\beta + j$

$(i,j).idR = 0$

Can be joined

Cannot be joined



Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2

Key:

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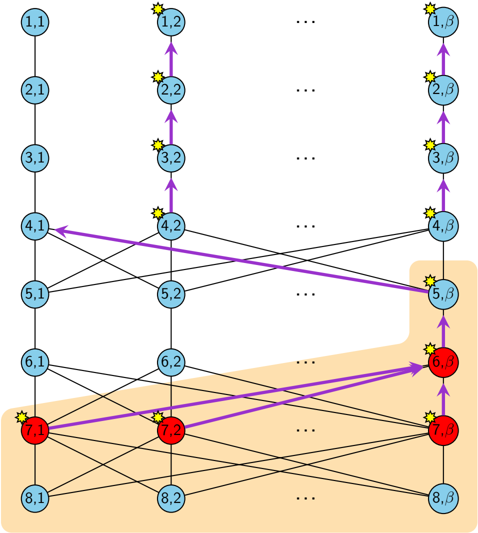

Datta et al, 2011

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β^2

Key:

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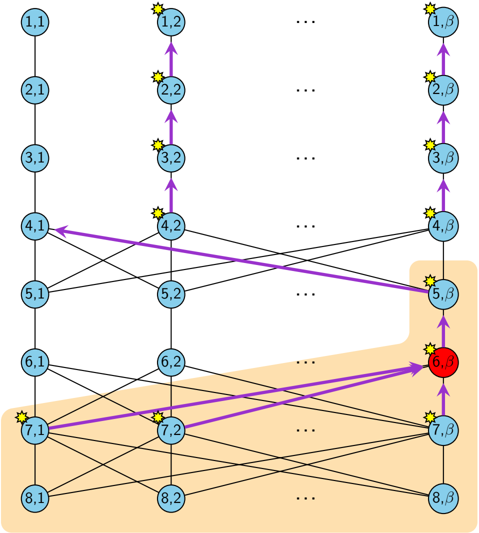
$(i,j).idR = 0$ (star)

Can be joined (blue)

Cannot be joined (red)



Datta et al, 2011

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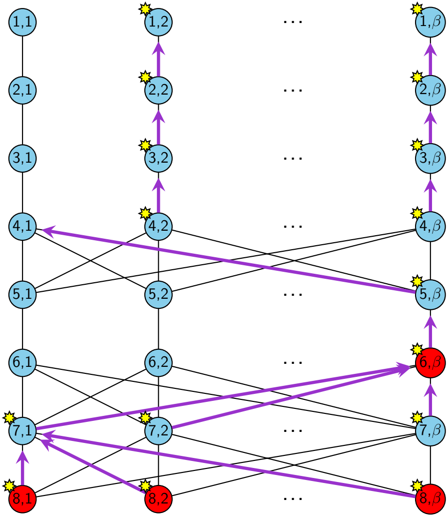

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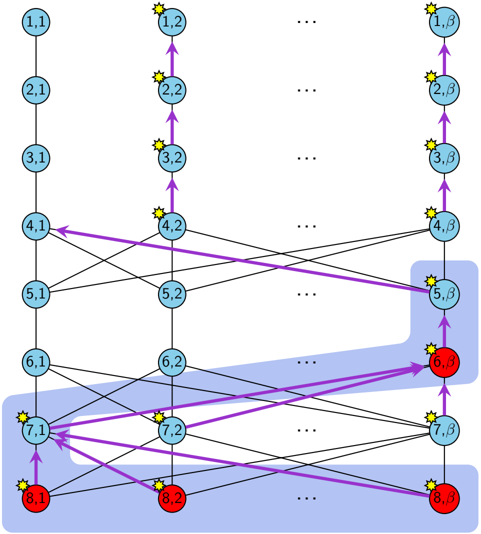

Datta et al, 2011

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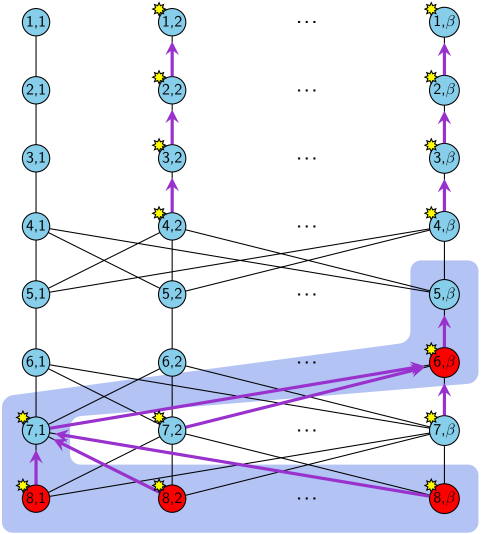

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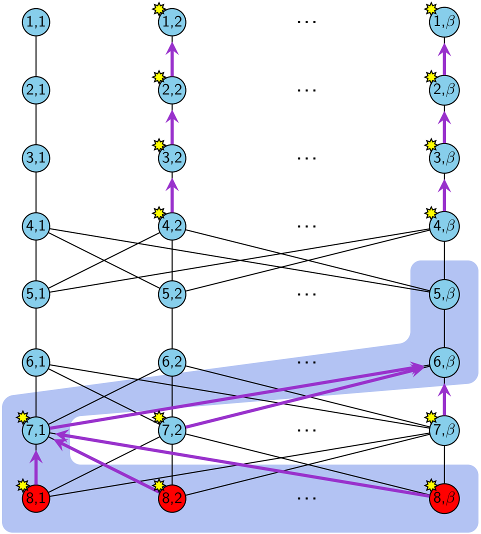

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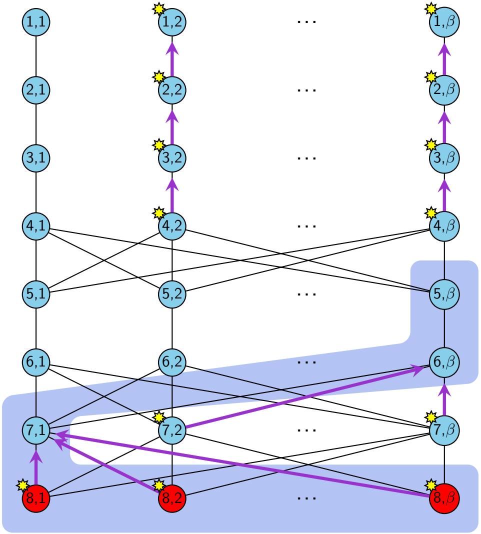

Datta et al, 2011

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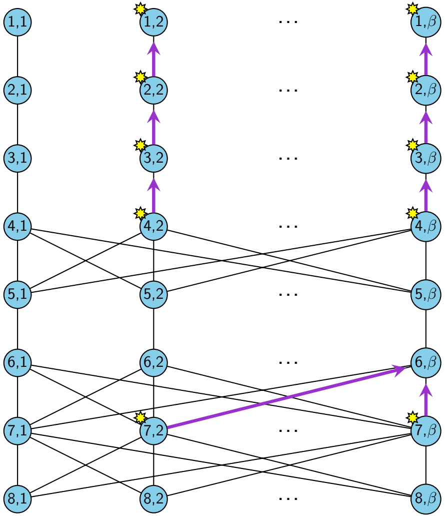
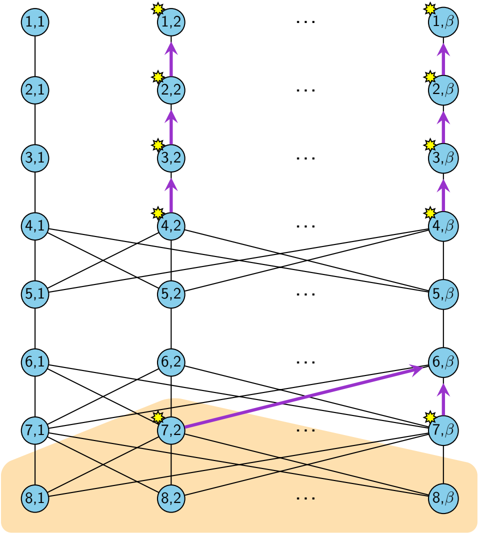


Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2



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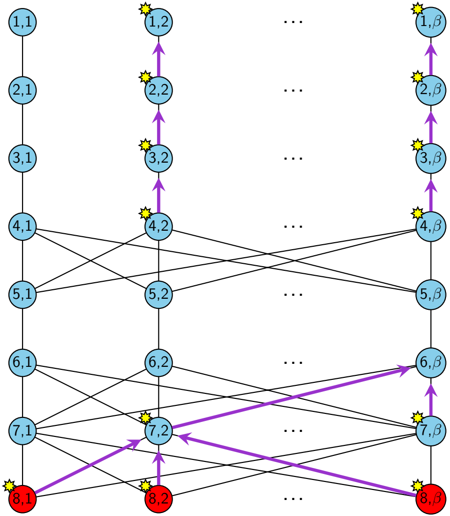

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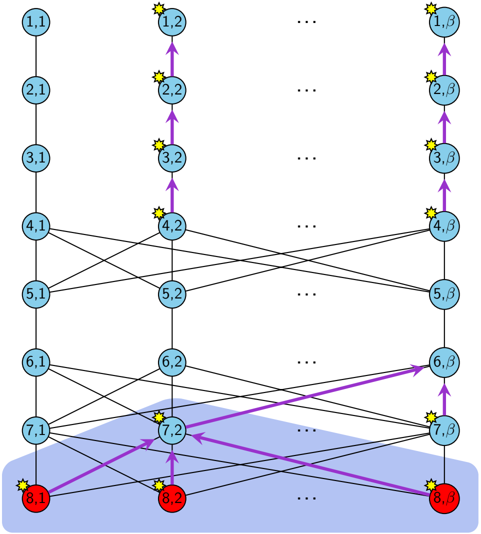

Datta et al, 2011

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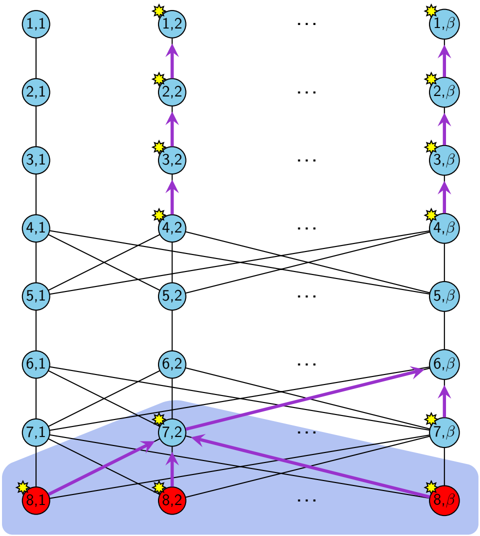

Datta et al, 2011

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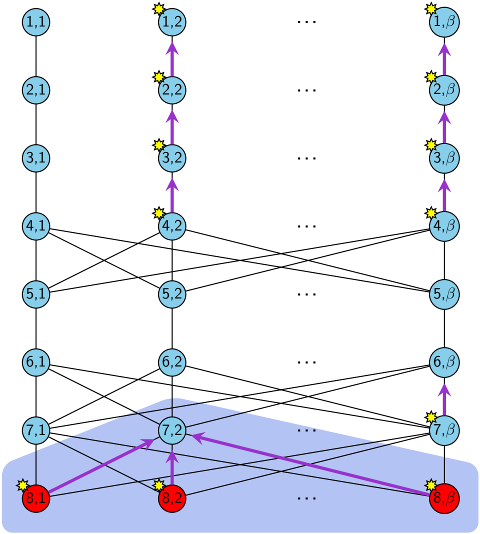

Datta et al, 2011

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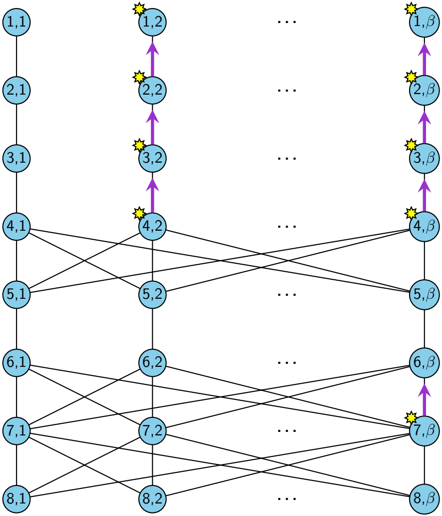

Datta et al, 2011

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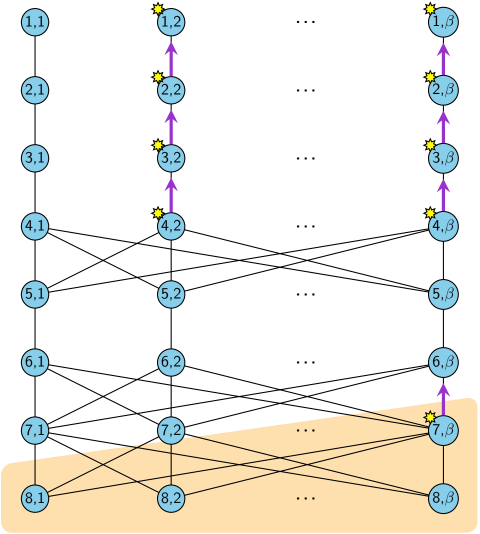

Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^2

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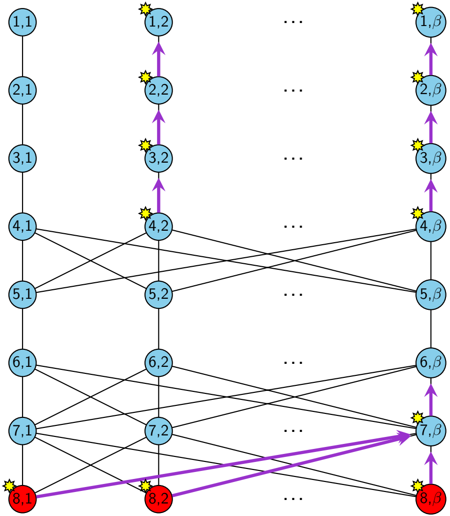

Datta et al, 2011

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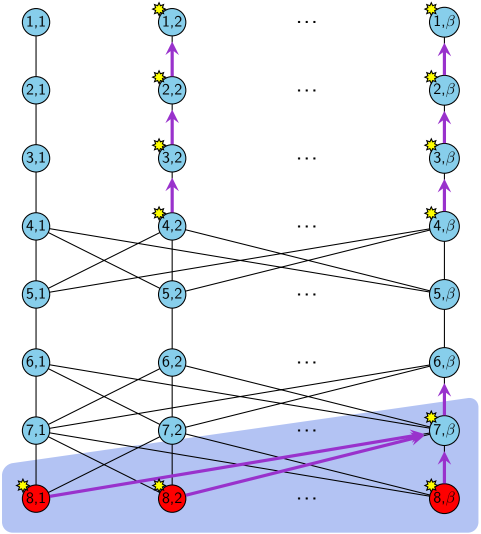

Datta et al, 2011

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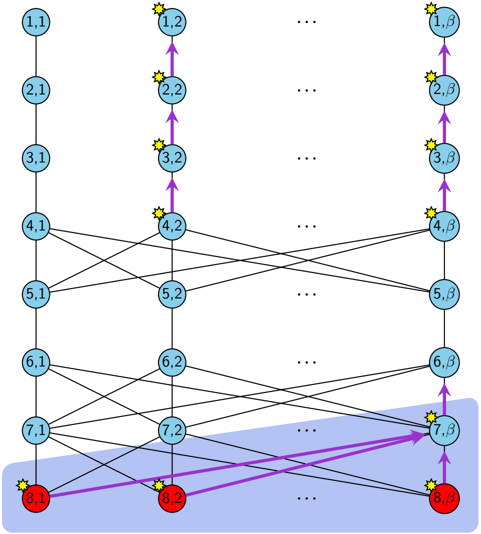

Datta et al, 2011

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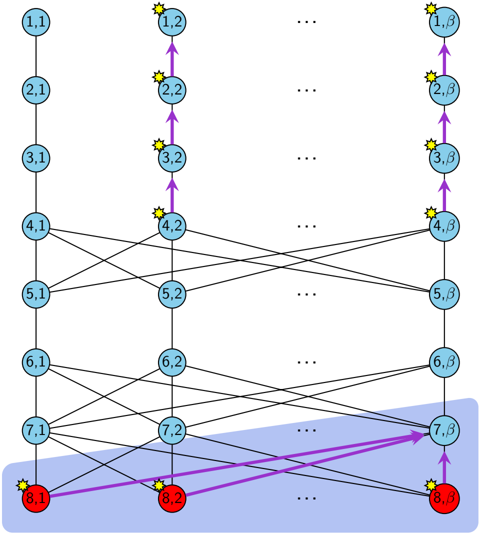
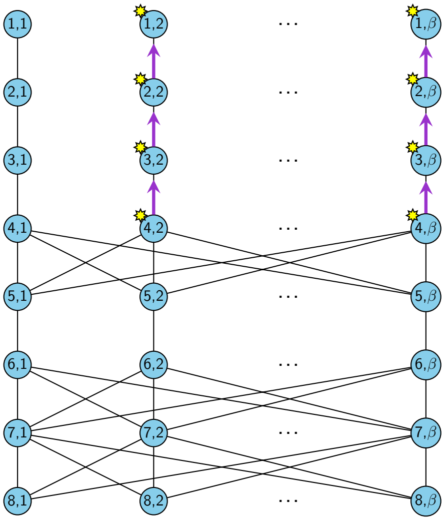


Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^3



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● Can be joined

● Cannot be joined

Datta et al, 2011

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β^3

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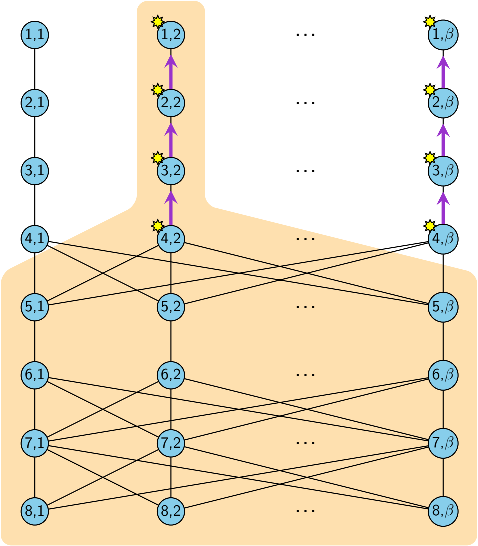


Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^3

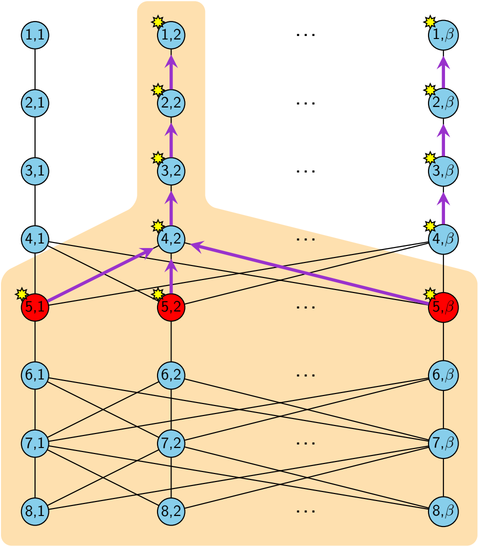
Key:

$(i,j).ID = (i-1)\beta + j$

$(i,j).idR = 0$ (star)

Can be joined (blue)

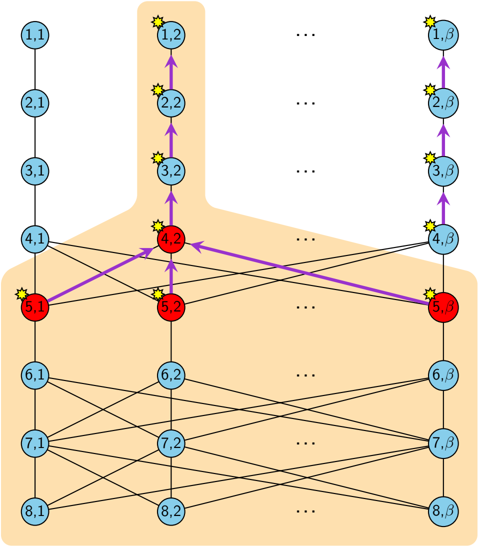
Cannot be joined (red)



Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

β^3



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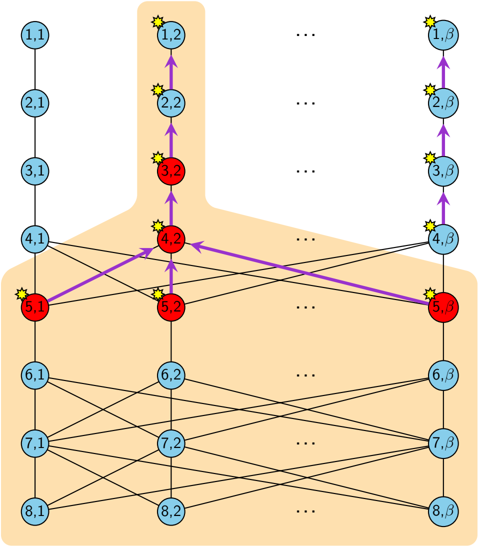

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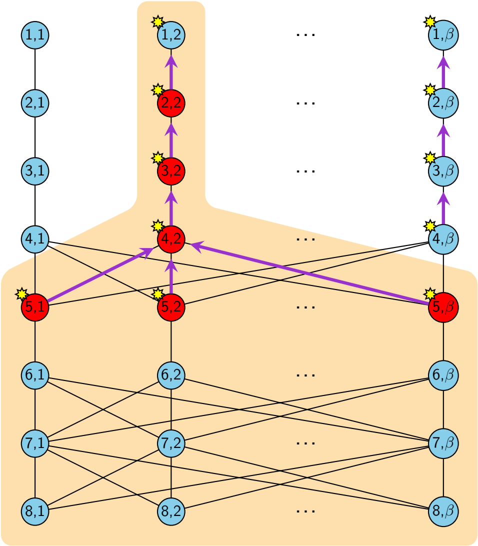
β^3



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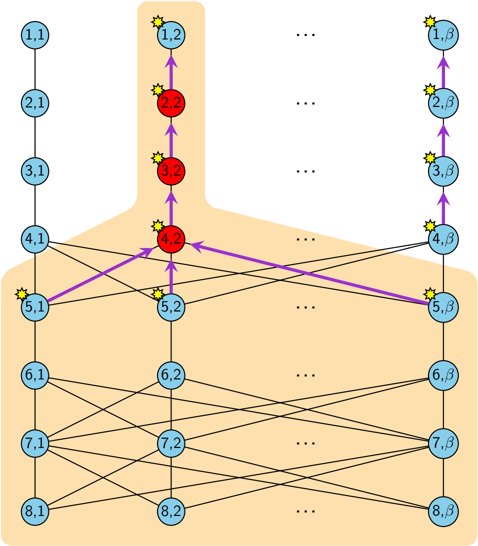

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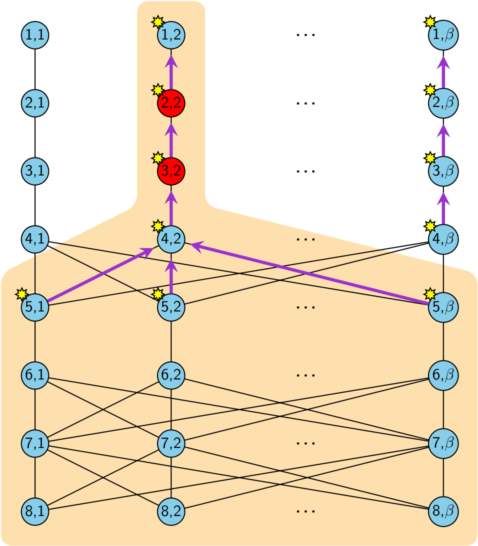

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Datta et al, 2011

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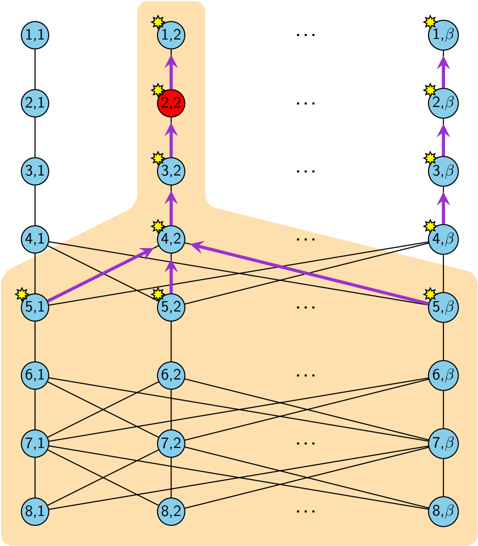

Datta et al, 2011

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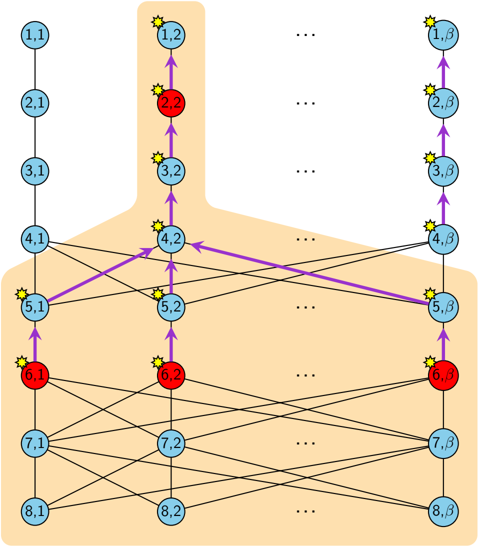

Key:

$(i, j).ID = (i - 1)\beta + j$

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Can be joined

Cannot be joined

Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

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Can be joined (blue)

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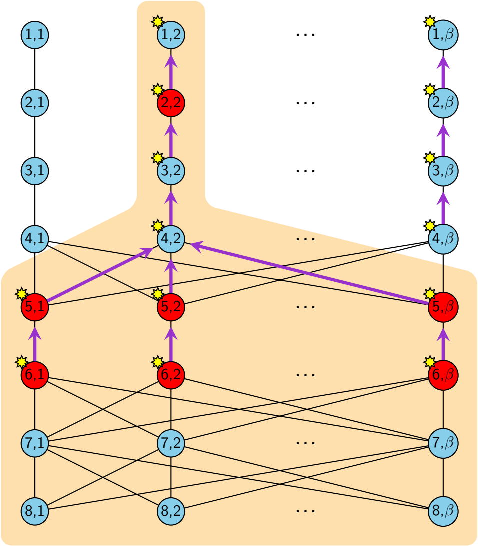

Datta et al, 2011

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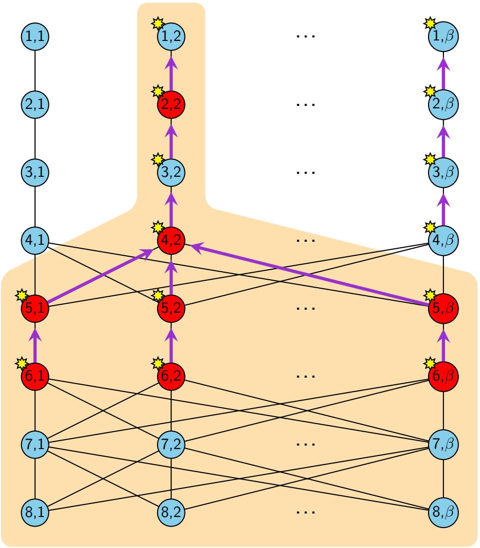
β^3



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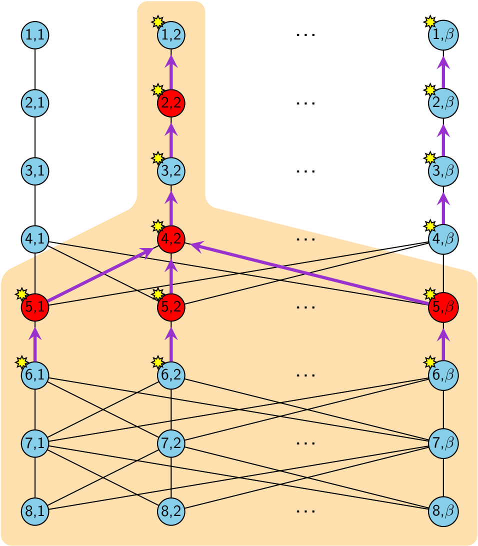

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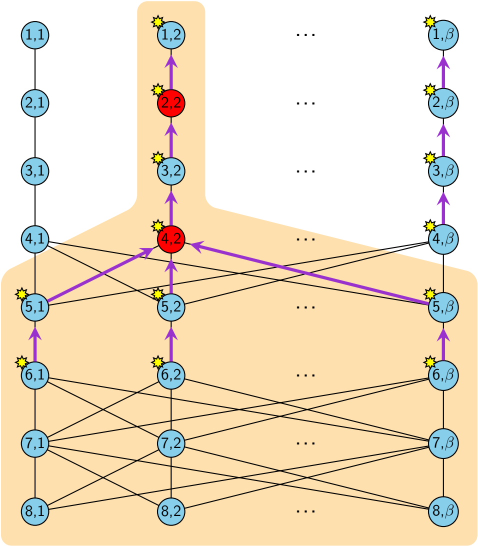

Datta et al, 2011

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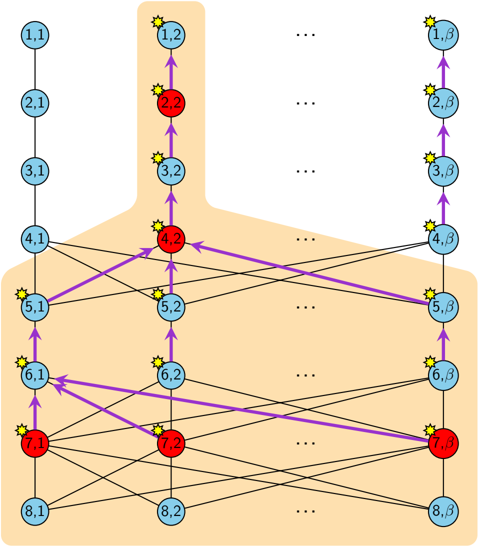

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Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

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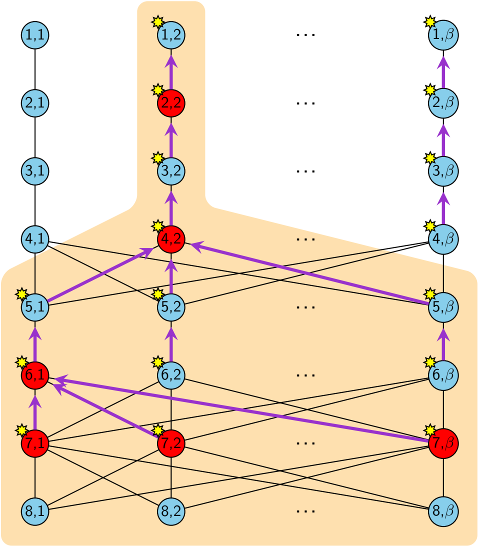

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Datta et al, 2011

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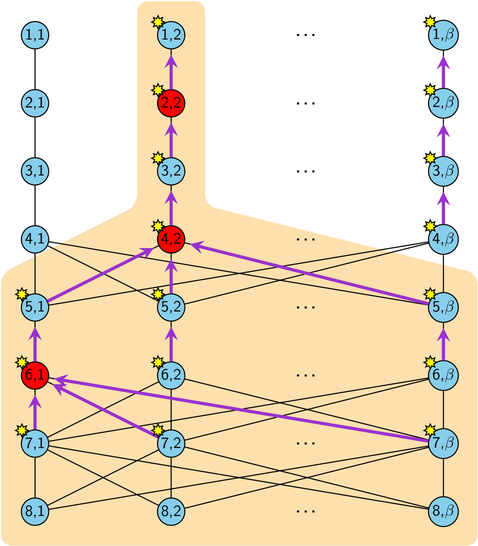

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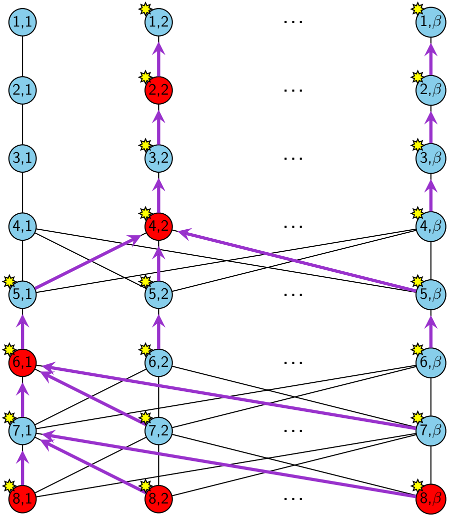

Datta et al, 2011

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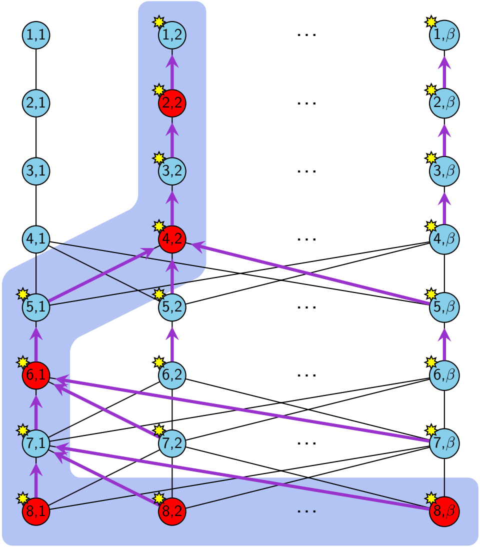

Datta et al, 2011

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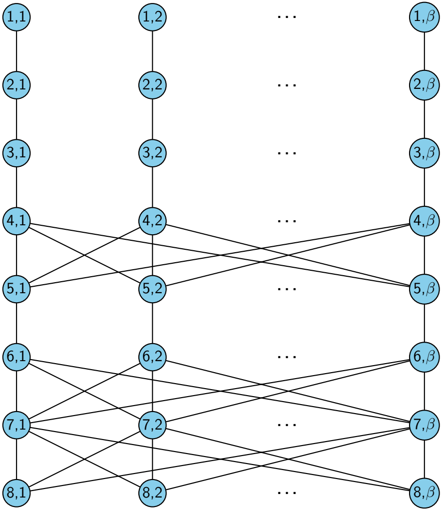
β^4



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Cannot be joined

Datta et al, 2011

Execution in $\Omega(n^4)$ steps: $\beta = \frac{n}{8}$

$$\beta = \Omega(n) \Rightarrow \overset{\beta^4}{\Omega(n^4)}$$

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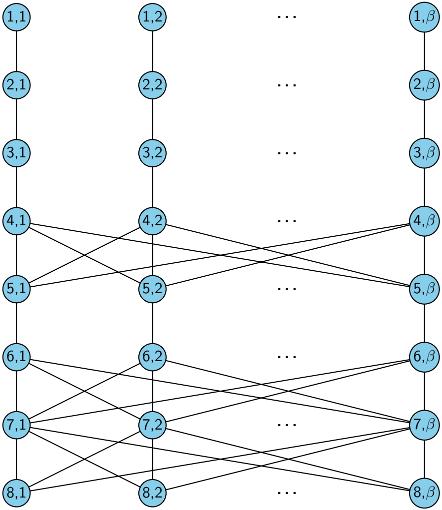
Cannot be joined



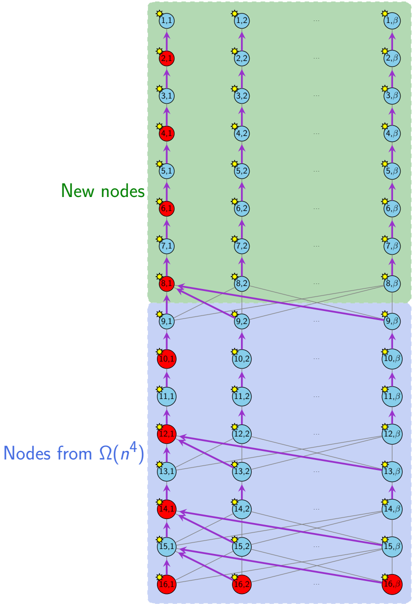
Datta et al, 2011

Network for $\Omega(n^5)$ steps

$\forall \alpha \geq 3$, $\exists$ networks and executions in $\Omega(n^{\alpha+1})$ steps.

Worst Case:

$$\Omega\left((2n)^{\frac{1}{4}\log_2(2n)}\right) \text{ steps}$$



Perspectives

Goal

Design a self-stabilizing leader election algorithm that stabilizes in $O(\mathcal{D})$ rounds.

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Hypotheses

- Unfair daemon
- Memory requirement of $\Theta(\log n)$ bits/process

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- With the knowledge of $D \geq \mathcal{D}$, ($D = O(\mathcal{D})$) : ✓

Perspectives

Goal

Design a self-stabilizing leader election algorithm that stabilizes in $O(\mathcal{D})$ rounds.

Hypotheses

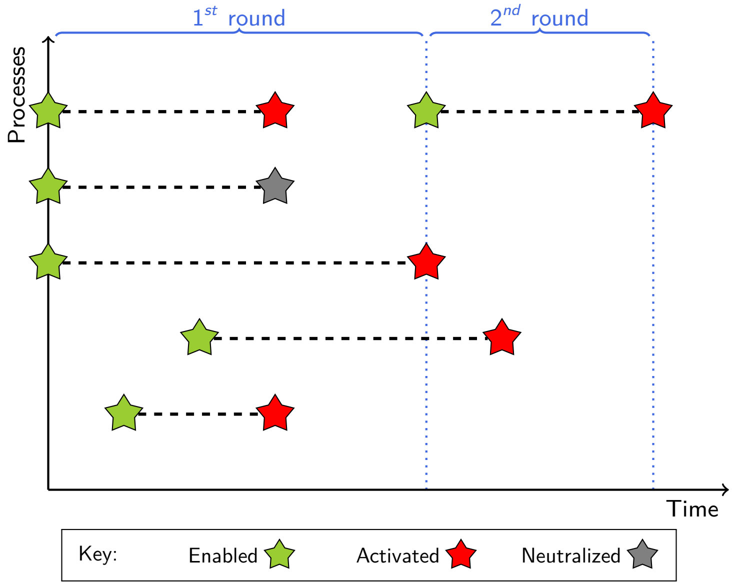
- Unfair daemon
- Memory requirement of $\Theta(\log n)$ bits/process

- With the knowledge of $D \geq \mathcal{D}$, $(D = O(\mathcal{D}))$: ✓
- Without any global knowledge : **??**

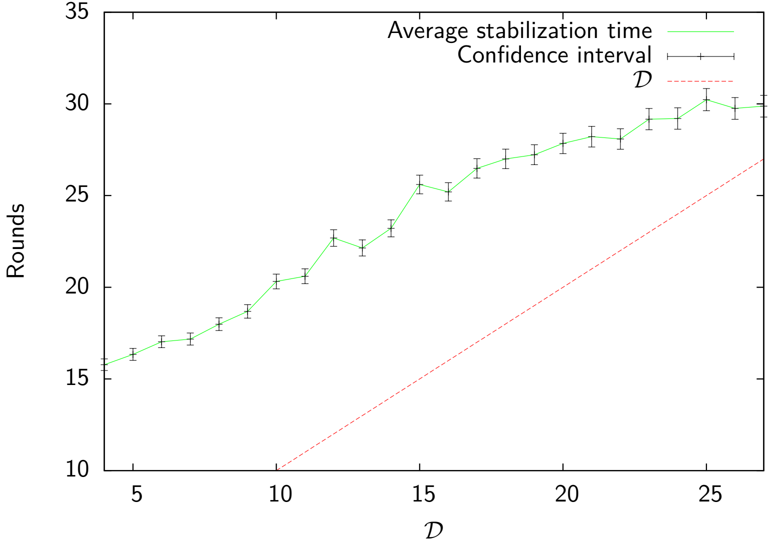
Thank you for your attention.

Do you have any questions ?

Rounds

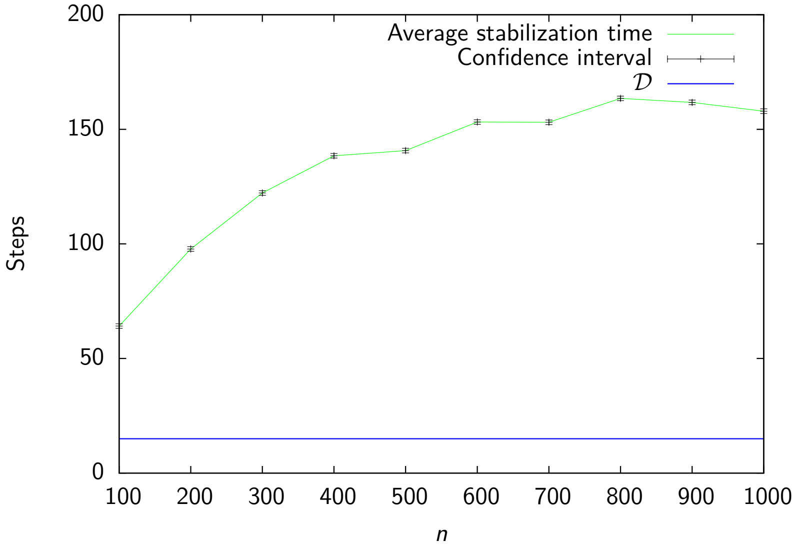

1st round
2nd round
Processes
Time
Key:
Enabled
Activated
Neutralized

Experimental Results



Average stabilization time in rounds in UDGs ($n = 1000$)

Experimental Results



Average stabilization time in steps in UDGs ($\mathcal{D} = 15$)